
SAT, CSP, and proofs

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Tutorial HVC'13

The grand plan for today

- Intro: the role of SAT, CSP and proofs in verification
- SAT – how it works, and how it produces proofs
- CSP - how it works, and how it produces proofs
- Making proofs smaller

Why SAT ?

Example: is $(x_1 \wedge (x_2 \vee \neg x_1))$ satisfiable ?

$x_1, x_2 \in \mathcal{B}$

- Applications in verification:
 - Formal verification:
 - (Bounded) model checking for hardware [1999 --]
 - Over a dozen commercial tools
 - (Bounded) model checking for software [2001 --]
 - CBMC, SAT-ABS, CLLVM, ...
 - Satisfiability Modulo Theories (SMT) [2003 --]
 - e.g. MS – Z3 used in dozens of software analysis tools (SymDiff, VCC, Havoc, Spec#, ...)

Why SAT ?

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$$x_1, x_2 \in \mathcal{B}$$

- Applications in verification:
 - Simulation:
 - Test generation for hardware
 - Test generation for software via SMT
 - MS-SAGE, KLEE, ...

Why CSP (Constraints Satisfaction Problem) ?

Example:

is $(\text{AllDiff}(x_1, x_2, x_3) \vee x_1 < x_2 + 3 \wedge x_2 > x_3 - 1)$ satisfiable ?

$x_1, x_2, x_3 \in [0..10] \cap \mathbb{Z}$

- Applications in verification:
 - Formal verification: ??
 - Simulation: test generation for hardware

Why CSP (Constraints Satisfaction Problem) ?

Example:

is $(\text{AllDiff}(x_1, x_2, x_3) \vee x_1 < x_2 + 3 \wedge x_2 > x_3 - 1)$ satisfiable ?

$x_1, x_2, x_3 \in [0..10] \cap \mathbb{Z}$

- A Higher-level modeling language
 - Can lead to an order of magnitude smaller model size.
 - Does not matter much in practice
- Certain constraints can be solved faster than in SAT
 - Some (e.g. “all-different”) can be solved directly in P

SAT and CSP



- SAT is crawling towards CSP
 - Various SAT solvers now support high-level constraints over **Boolean variables**:
 - **Cripto-minisat** supports XOR constraints
 - **MiniSat+** supports cardinality constraints $\sum w_i x_i \leq c$

- CSP is crawling towards SAT:
 - Some solvers support reduction to SAT
 - Solution strategy now mimics SAT

Why proofs ?

- Traditionally the focus was on finding models
 - No information was given in case of UNSAT
- As of Chaff (2003 --) solvers produce proofs
 - Originally just to validate result

Why proofs ?

Several killer-applications (SAT):

- Validate UNSAT results
- From the proof we can extract an **unsat core**
 - Used in formal verification [AM03, KKB09, BKOSSB07...]
- Uses of the proof itself:
 - Interpolation-based model checking [M03].
- Can we foresee usage for **proofs in CSP** ?

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CNF-SAT

- **Conjunctive Normal Form:** Conjunction of disjunction of literals. Example:

$$(\neg x_1 \vee \neg x_2) \wedge (x_2 \vee x_4 \vee \neg x_1) \wedge \dots$$

- Polynomial transformation to CNF due to Tseitin (1970)
 - Requires adding auxiliary variables.

Main steps – SAT

SAT

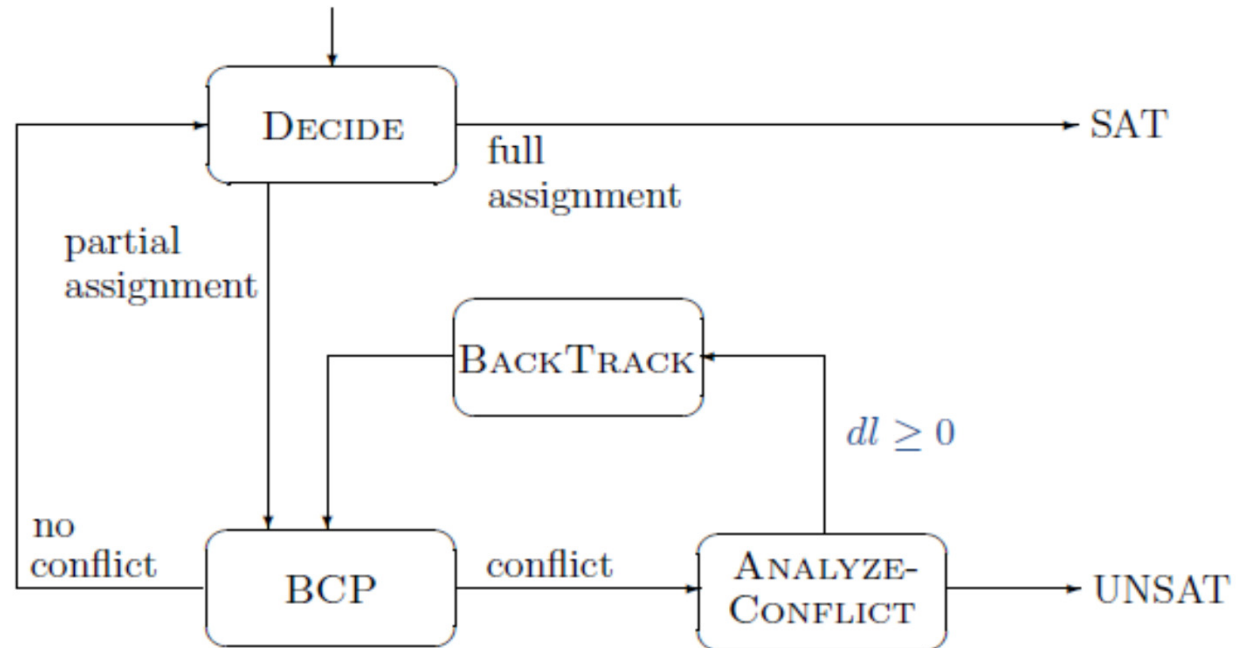
- “Decide”
 - Variable, value
- “Boolean Constraints Propagation (BCP)”
 - infer implied assignments
- “Analyze conflict”
 - applies learning
 - computes backtracking level

About that “constraints propagation”

- given $(\neg x_1 \vee \neg x_2) \wedge (x_2 \vee x_4 \vee \neg x_1) \wedge \dots$

BCP: $x_1 = 1 \Rightarrow x_2 = 0 \Rightarrow x_4 = 1 \Rightarrow \dots$

SAT essentials

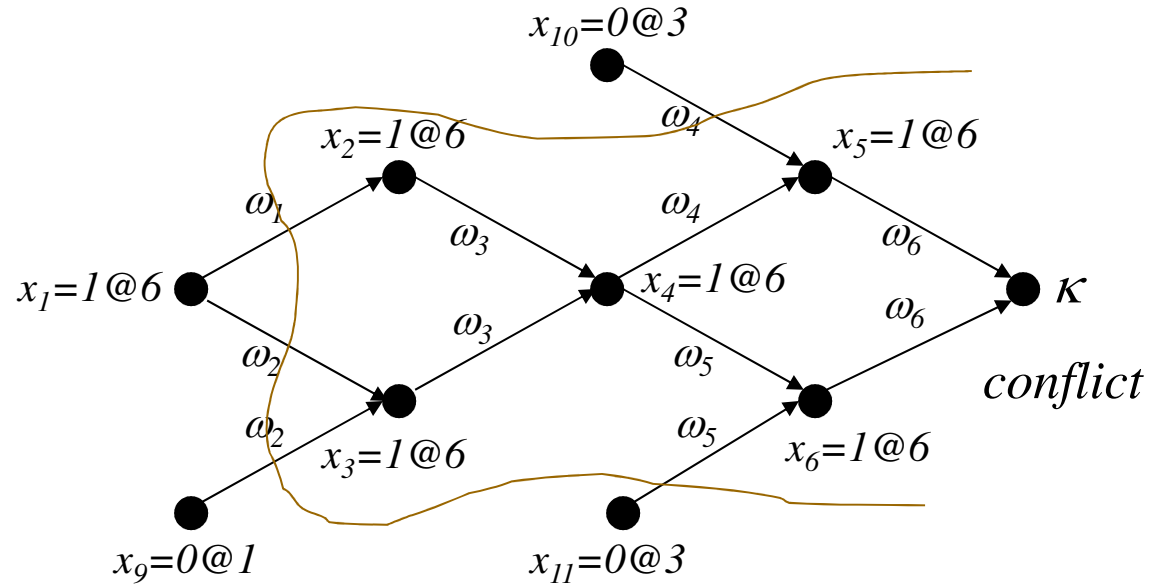


Implication graphs and learning

Current truth assignment: $\{x_9=0@1, x_{10}=0@3, x_{11}=0@3, x_{12}=1@2, x_{13}=1@2\}$

Current decision assignment: $\{x_1=1@6\}$

- $\omega_1 = (\neg x_1 \vee x_2)$
- $\omega_2 = (\neg x_1 \vee x_3 \vee x_9)$
- $\omega_3 = (\neg x_2 \vee \neg x_3 \vee x_4)$
- $\omega_4 = (\neg x_4 \vee x_5 \vee x_{10})$
- $\omega_5 = (\neg x_4 \vee x_6 \vee x_{11})$
- $\omega_6 = (\neg x_5 \vee \neg x_6)$
- $\omega_7 = (x_1 \vee x_7 \vee \neg x_{12})$
- $\omega_8 = (x_1 \vee x_8)$
- $\omega_9 = (\neg x_7 \vee \neg x_8 \vee \neg x_{13})$



We learn the *conflict clause* $\omega_{10} : (\neg x_1 \vee x_9 \vee x_{11} \vee x_{10})$

and backtrack to the highest (deepest) dec. level in this clause (6). 15

Implication graph, flipped assignment

$$\omega_1 = (\neg x_1 \vee x_2)$$

$$\omega_2 = (\neg x_1 \vee x_3 \vee x_9)$$

$$\omega_3 = (\neg x_2 \vee \neg x_3 \vee x_4)$$

$$\omega_4 = (\neg x_4 \vee x_5 \vee x_{10})$$

$$\omega_5 = (\neg x_4 \vee x_6 \vee x_{11})$$

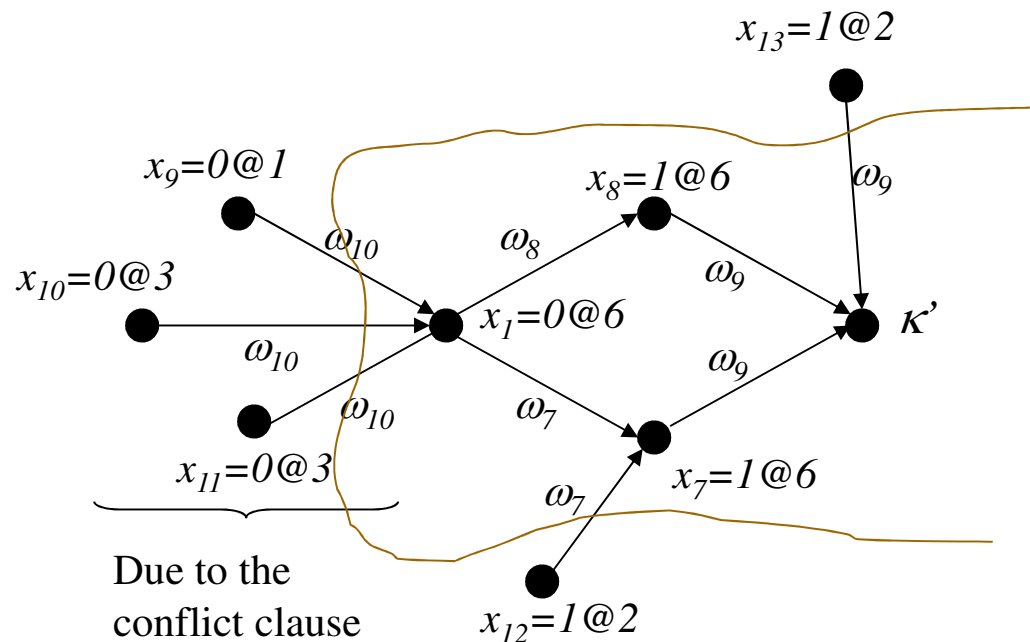
$$\omega_6 = (\neg x_5 \vee x_6)$$

$$\omega_7 = (x_1 \vee x_7 \vee \neg x_{12})$$

$$\omega_8 = (x_1 \vee x_8)$$

$$\omega_9 = (\neg x_7 \vee \neg x_8 \vee \neg x_{13})$$

$$\omega_{10} : (\neg x_1 \vee x_9 \vee x_{11} \vee x_{10})$$



We learn the *conflict clause* $\omega_{11} : (\neg x_{13} \vee x_9 \vee x_{10} \vee x_{11} \vee \neg x_{12})$

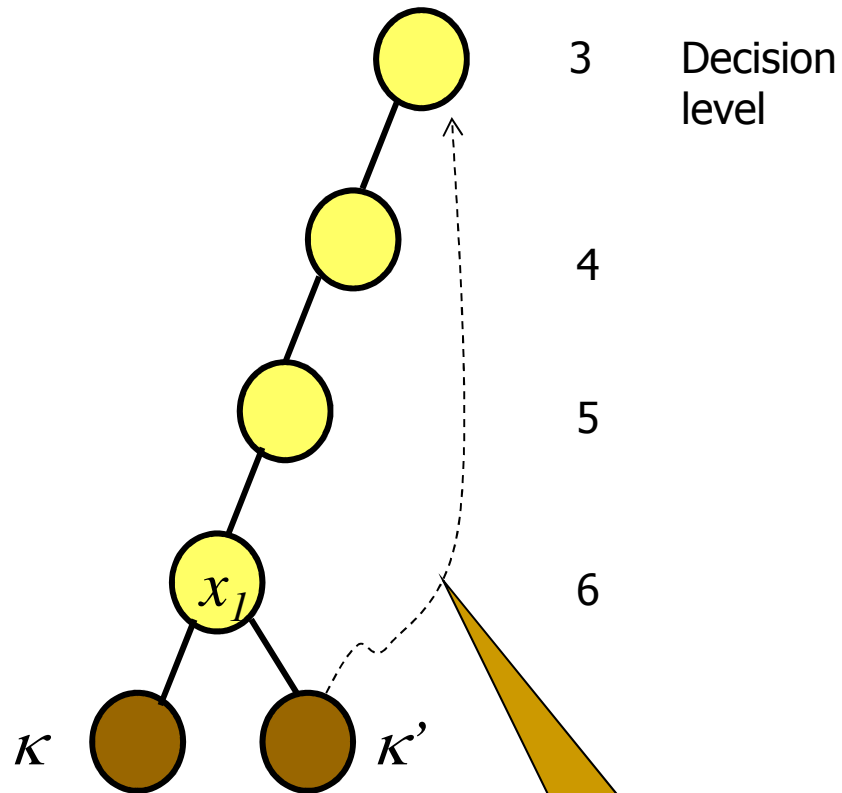
and backtrack to the highest (deepest) dec. level in this clause (3). 16

Non-chronological backtracking

Which assignments caused the conflicts ?

$x_9 = 0@1$
 $x_{10} = 0@3$
 $x_{11} = 0@3$
 $x_{12} = 1@2$
 $x_{13} = 1@2$

*These assignments
Are sufficient for
Causing a conflict.*



Backtrack to decision level 3

Non-chronological backtracking

Learning and resolution

- Learning of a clause = inference by resolution.
 - To be explained
- This is the key for producing a machine-checkable proof

Resolution

- ...By example:

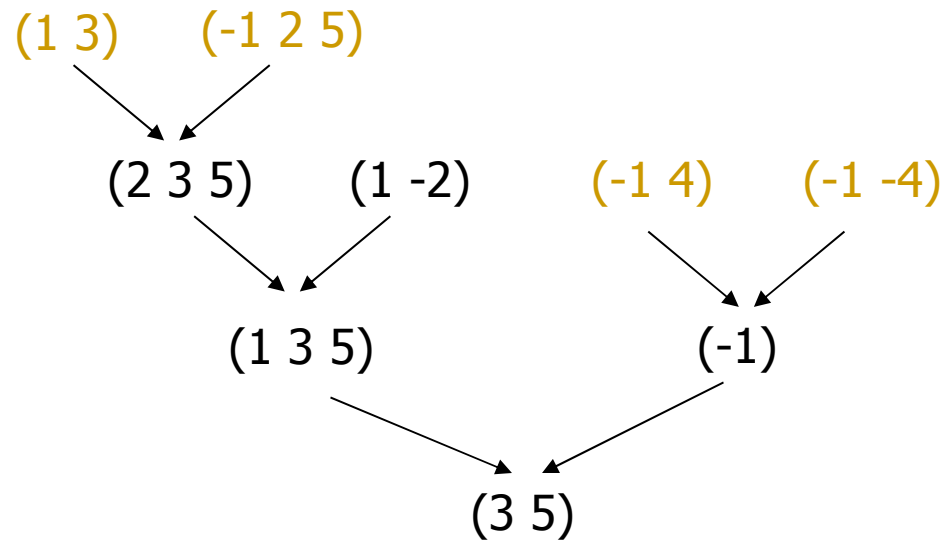
$$\frac{(x_1 \vee x_2) \quad (\neg x_1 \vee x_3 \vee x_4)}{(x_2 \vee x_3 \vee x_4)}$$

- Formally:

$$\frac{(a_1 \vee \dots \vee a_n \vee \beta) \quad (b_1 \vee \dots \vee b_m \vee (\neg\beta))}{(a_1 \vee \dots \vee a_n \vee b_1 \vee \dots \vee b_m)} \quad \text{(Binary Resolution)}$$

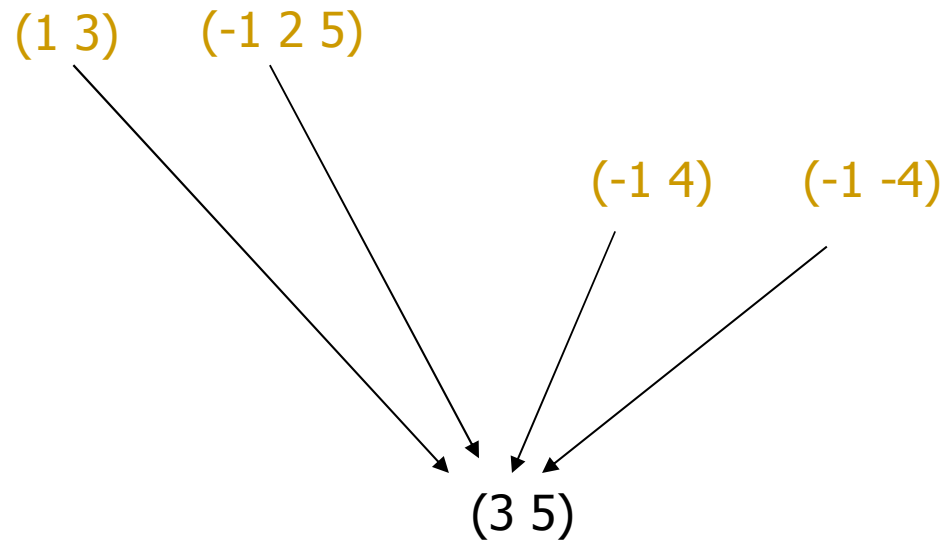
Resolution proof

A proof: $(1\ 3) \wedge (-1\ 2\ 5) \wedge (-1\ 4) \wedge (-1\ -4) \vdash (3\ 5)$



Resolution proof \Rightarrow Hyper resolution proof

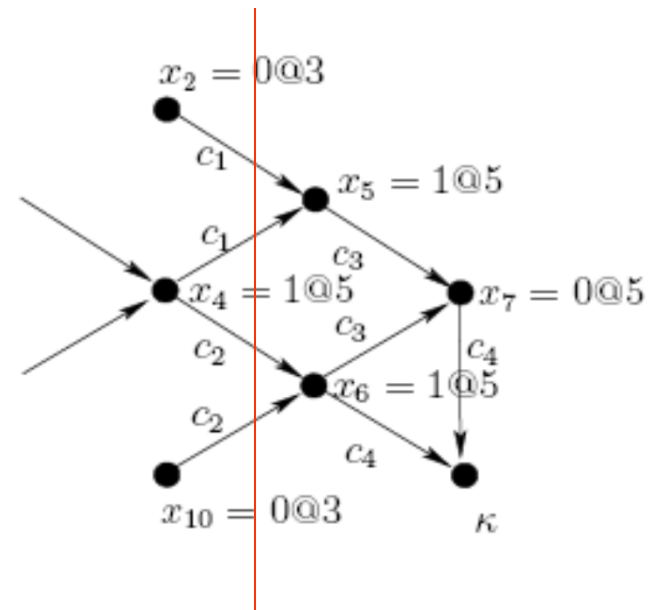
A proof: $(1\ 3) \wedge (-1\ 2\ 5) \wedge (-1\ 4) \wedge (-1\ -4) \vdash (3\ 5)$



Conflict clauses and resolution

- Consider the following example:

$$\begin{aligned}c_1 &= (\neg x_4 \vee x_2 \vee x_5) \\c_2 &= (\neg x_4 \vee x_{10} \vee x_6) \\c_3 &= (\neg x_5 \vee \neg x_6 \vee \neg x_7) \\c_4 &= (\neg x_6 \vee x_7) \\&\vdots \\&\vdots\end{aligned}$$



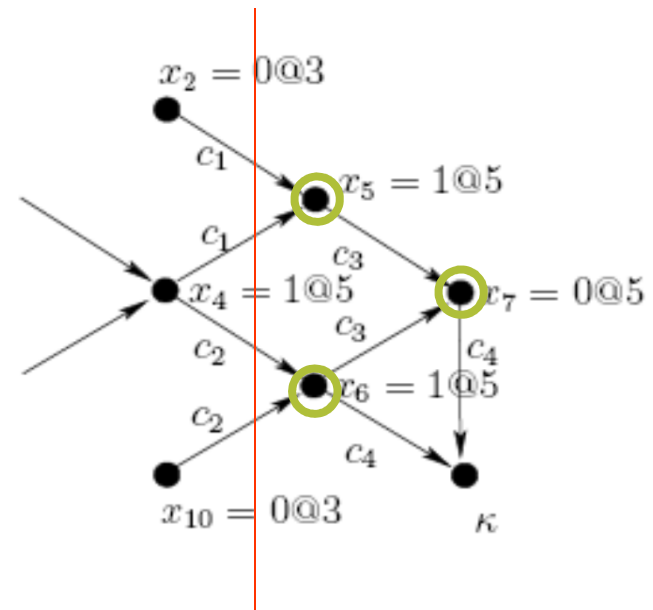
- Conflict clause: $c_5: (x_2 \vee \neg x_4 \vee x_{10})$
- We show that c_5 is inferred by resolution from c_1, \dots, c_4

Conflict clauses and resolution

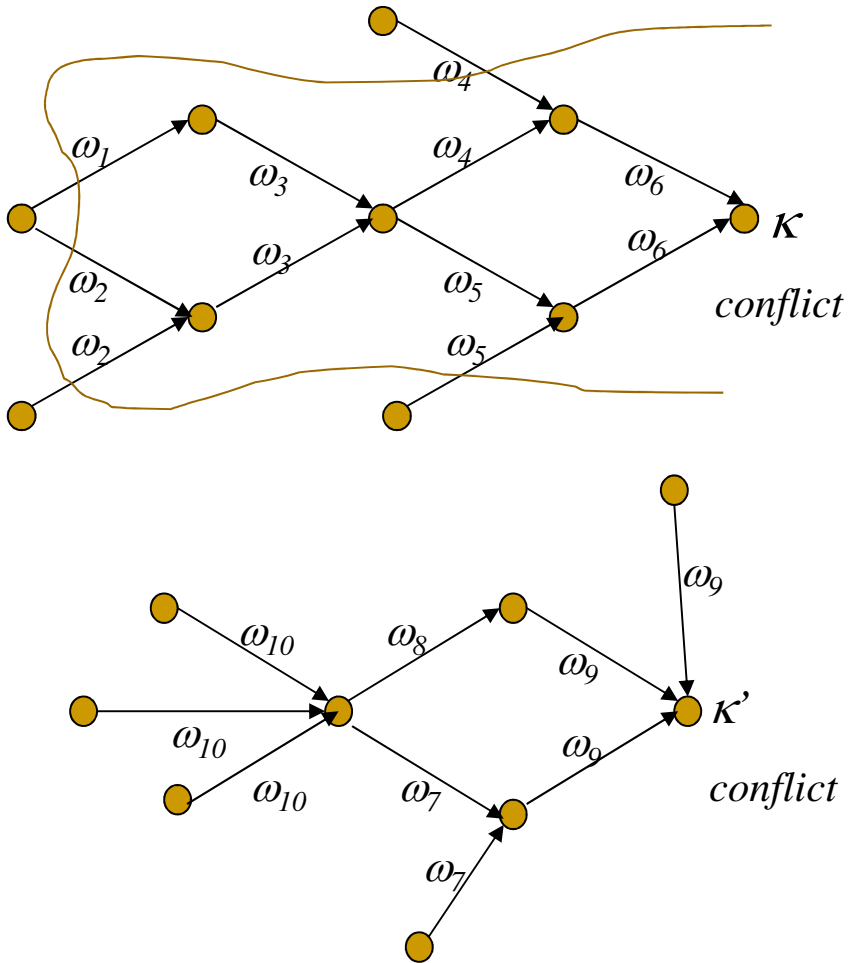
- **Conflict clause:** $c_5: (x_2 \vee \neg x_4 \vee x_{10})$

$$\begin{aligned}
 c_1 &= (\neg x_4 \vee x_2 \vee x_5) \\
 c_2 &= (\neg x_4 \vee x_{10} \vee x_6) \\
 c_3 &= (\neg x_5 \vee \neg x_6 \vee \neg x_7) \\
 c_4 &= (\neg x_6 \vee x_7) \\
 \vdots & \quad \quad \quad \vdots
 \end{aligned}$$

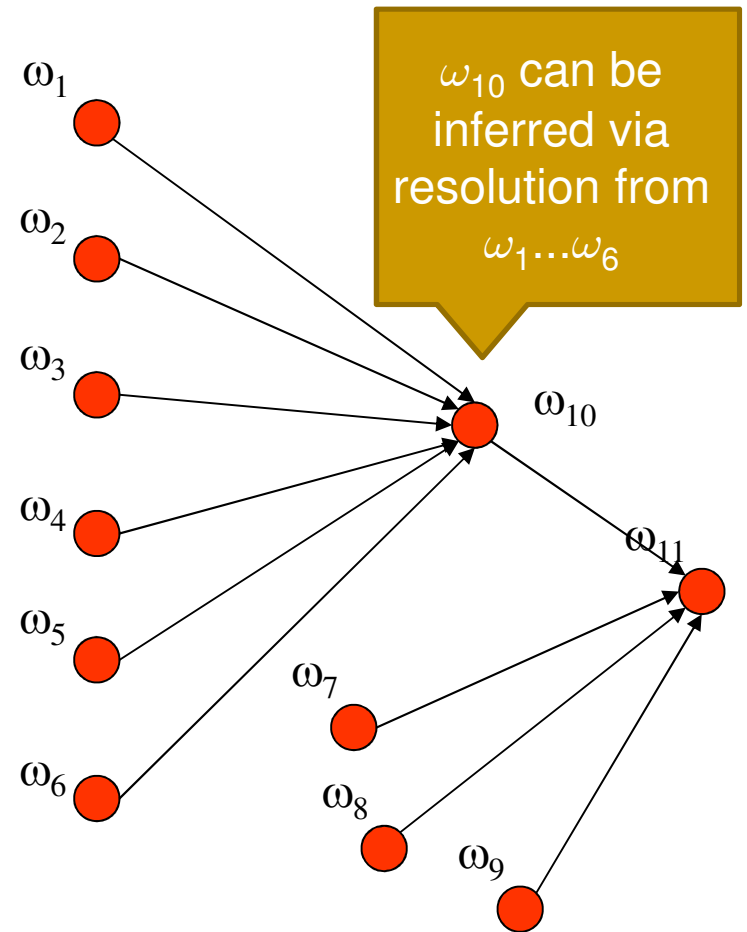
- **BCP order:** x_4, x_5, x_6, x_7
 - $T1 = \text{Res}(c_4, c_3, x_7) = (\neg x_5 \vee \neg x_6)$
 - $T2 = \text{Res}(T1, c_2, x_6) = (\neg x_4 \vee \neg x_5 \vee x_{10})$
 - $T3 = \text{Res}(T2, c_1, x_5) = (x_2 \vee \neg x_4 \vee x_{10})$



The Resolution-Graph



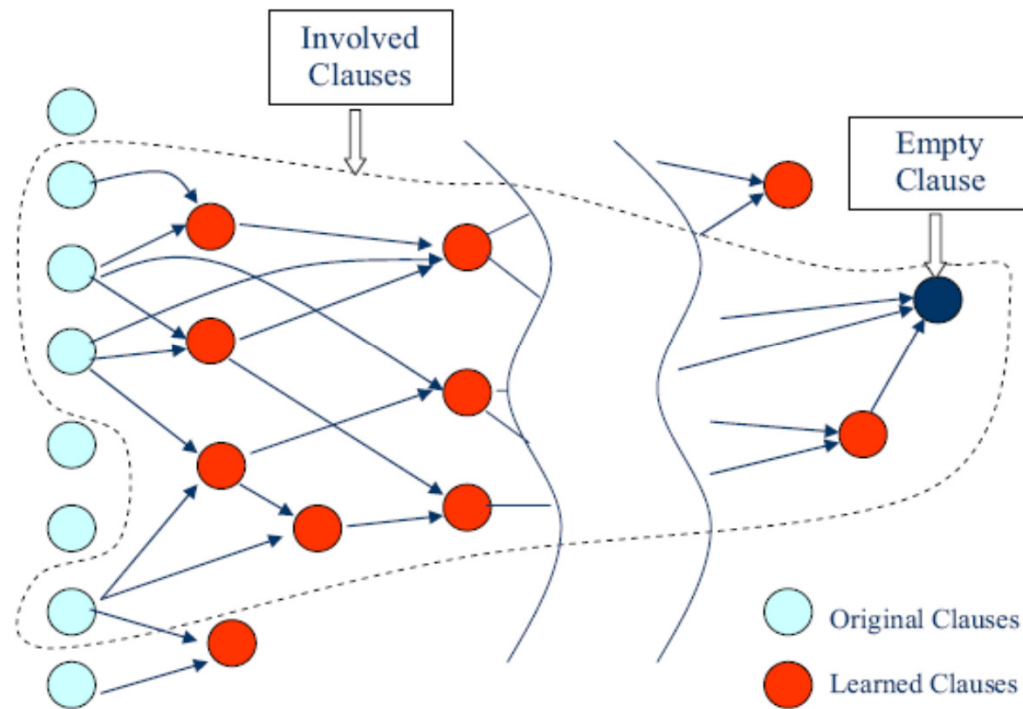
(Hyper) Resolution Graph



The resolution graph

What is it good for ?

Example: for computing an **Unsatisfiable core**



[Picture Borrowed from Zhang, Malik SAT'03]

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Main steps – SAT and CSP*

SAT

- “Decide”
 - Variable, value
- “Boolean Constraints Propagation (BCP)”
 - infer implied assignments
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 - computes backtracking level

CSP

- *Same*
- ~~“Boolean Constraints Propagation (CP)”~~
 - same
- *Same*

*As implemented in PCS / Michael Veksler

About that “constraints propagation”

- **Given** $x_1, x_2, x_3 \in [1..3]$, $\text{AllDifferent}(x_1, x_2, x_3)$

CP: $x_1 = 1 \Rightarrow x_2, x_3 \in [2..3]$

What about CSP proofs ?

- SAT solvers generate proofs:
 - From initial clauses to ().
 - Inference is via the binary-resolution rule.
- Unlike SAT solvers, CSPs:
 - have non-Boolean domains, and
 - non-clausal constraints.
- Can this gap be bridged?
 - The following is based on [SV10]

Signed CNF

... by examples:

- A **positive signed literal**: $a \in \{1, 2, 3\}$.
- A **negative signed literal**: $a \in \overline{\{1, 2, 4\}}$.
- A **signed clause** is a disjunction of signed literals. e.g.,

$$(a \in \{1, 5\} \vee b \in \overline{\{4\}})$$

Signed resolution

- A binary-resolution rule for signed-CNF:

$$\frac{(Literals_1 \vee x \in A) \quad (x \in B \vee Literals_2)}{(Literals_1 \vee x \in A \cap B \vee Literals_2)} \text{ (sRes}(x))$$

- Signed-clauses ✓
- What about other constraints ?
e.g. \neq , \leq , $\text{allDifferent}(v_1, \dots, v_k)$

should we just convert CSP to signed CNF?

Signed resolution

- Q: should we just convert CSP to signed CNF?
- A: No, because it is generally inefficient:
 - e.g., $x \neq y$ requires:

$$(x \in \overline{\{1\}} \vee y \in \overline{\{1\}}) \wedge (x \in \overline{\{2\}} \vee y \in \overline{\{2\}}) \wedge \dots$$

Towards a solution...

- Solution: introduce clauses *lazily*.
- Consider a general constraint c , such that:
 - In the context of $l_1 \wedge l_2 \wedge \dots \wedge l_n$,
 - propagation of c implies l :

$$(l_1 \wedge l_2 \wedge \dots \wedge l_n \wedge c) \rightarrow l$$

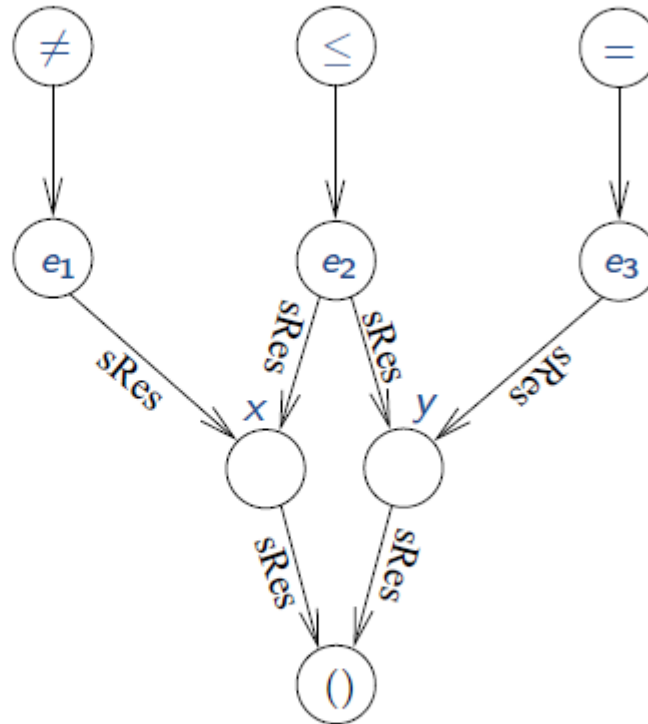
Towards a solution...

$$(l_1 \wedge l_2 \wedge \dots \wedge l_n \wedge c) \rightarrow l$$

- Find an **explanation clause** e such that:

- e is not too strong: $c \rightarrow e$
- e is strong enough: $(l_1 \wedge l_2 \wedge \dots \wedge l_n \wedge e) \rightarrow l$

The structure of a CSP proof



e_1, e_2, e_3 – explanation clauses.

Explanation rules

For every constraint there is an explanation clause:

$$\frac{\langle constraint \rangle}{\langle explanation clause \rangle} (\langle rule name \rangle)$$

Explanation rules – example 1

- Constraint: $x \neq y$

$$\frac{x \neq y}{x \in \overline{\{m\}} \vee y \in \overline{\{m\}}} (Ne(m))$$

parameterized

m = the value that triggered the rule

Explanation rules – example 1

Propagation:

- context: $h_1 : (x = 1), \quad h_2 : (y \in [1..100]).$
- constraint: $c : x \neq y.$
- implies: $l : (y \in [2..100]).$

$$e : (x \in \overline{\{1\}} \vee y \in \overline{\{1\}}) \quad // \text{Ne}(1)$$

... *indeed*:

- $c \xrightarrow{\text{Ne}(1)} e$
- $(h_1 \wedge h_2 \wedge e) \longrightarrow l$

Explanation rules – example 2

- Constraint: $x \leq y$

$$\frac{x \leq y}{(x \in (-\infty, m] \vee y \in [m + 1, \infty))} (LE(m))$$

Instantiate m with $\max(\text{domain}(y))$

Explanation rules – example 2

Propagation:

- context: $l_1 : (x \in [1..3]), l_2 : (y \in [0..2])$
- constraint: $c : x \leq y.$
- implies: $l : x \in [1..2]$

Explanation:

- $e : (x \in (-\infty, 2] \vee y \in [3, \infty)). \quad // = LE(2)$

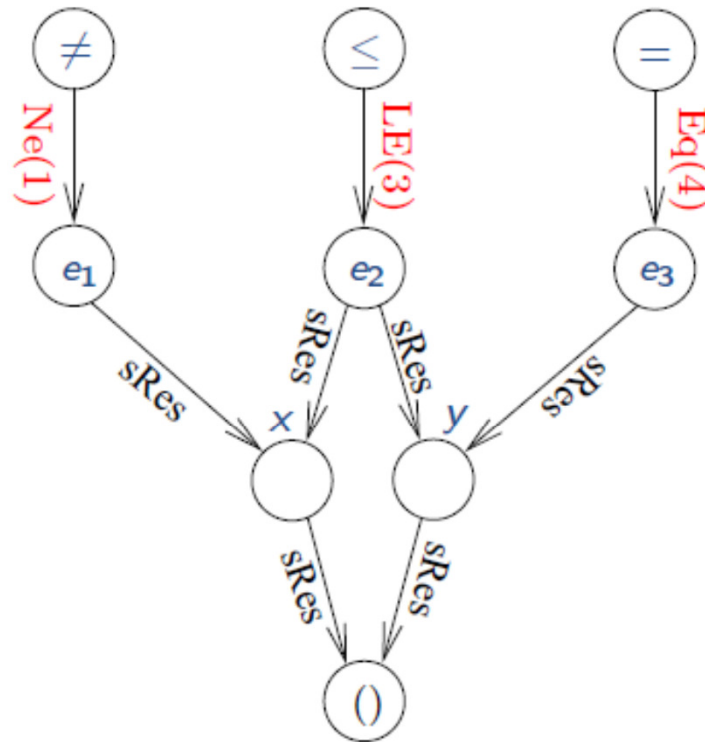
...indeed:

- $c \xrightarrow{LE(2)} e$
- $(l_1 \wedge l_2 \wedge e) \longrightarrow l$

Each constraint has its rule ...

Constraint	Name	Inference rule
$a \neq b$	$Ne(m)$	$\frac{a \neq b}{(a \neq m \vee b \neq m)}$
$x \leq y$	$LE(m)$	$\frac{x \leq y}{(x \in (-\infty, m] \vee y \in [m + 1, \infty))}$
$a = b$	$Eq(D)$	$\frac{a = b}{(a \notin D \vee b \in D)}$
$a \leq b + c$	$LE_+(m, n)$	$\frac{a \leq b + c}{(a \in (-\infty, m + n] \vee b \in [m + 1, \infty) \vee c \in [n + 1, \infty))}$
$a = b + c$	$EQ_+^a(l_b, u_b, l_c, u_c)$	$\frac{a = b + c}{(a \in [l_b + l_c, u_b + u_c] \vee b \notin [l_b, u_b] \vee c \notin [l_c, u_c])}$
$AllDiff(v_1, \dots, v_k)$	$AD(D, V)$	$\frac{AllDiff(v_1, \dots, v_k)}{(\forall v \in V v \notin D)}$
\vdots	\vdots	\vdots

So this is how the proof looks like...



e_1, e_2, e_3 – explanation clauses.

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Minimizing the core

- The proof is not unique.
 - Different proofs / different cores.
- Can we find a **minimum / minimal / smaller** cores/proofs?

Minimizing the core

- **Core** compression

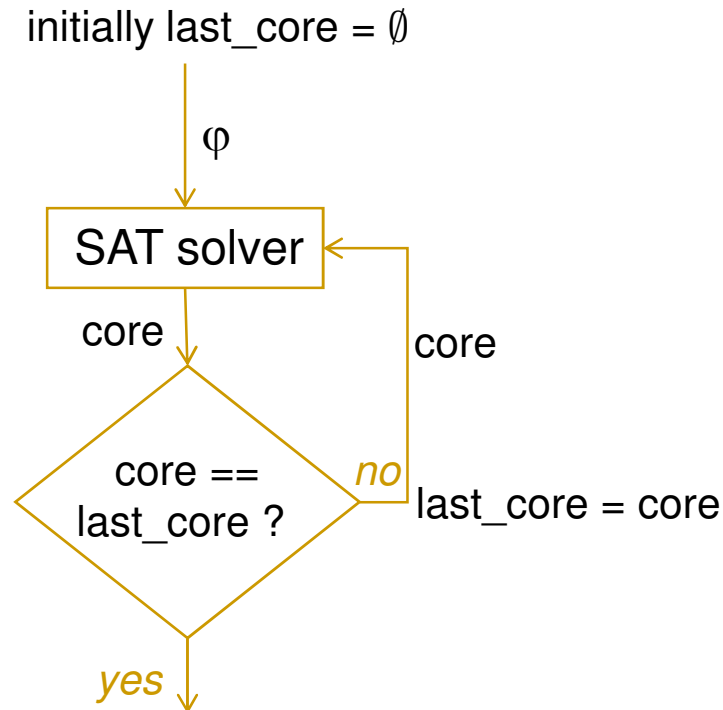
- Smaller core [ZM03, ...]
- Minimal core [DHN06, ...]
- Min-core-biased search [NRS'13]

- **Proof** compression:

- Exponential-time transformations [GKS'06]
- Linear time transformations
 - “Recycle pivots” [BFHSS'08], ...

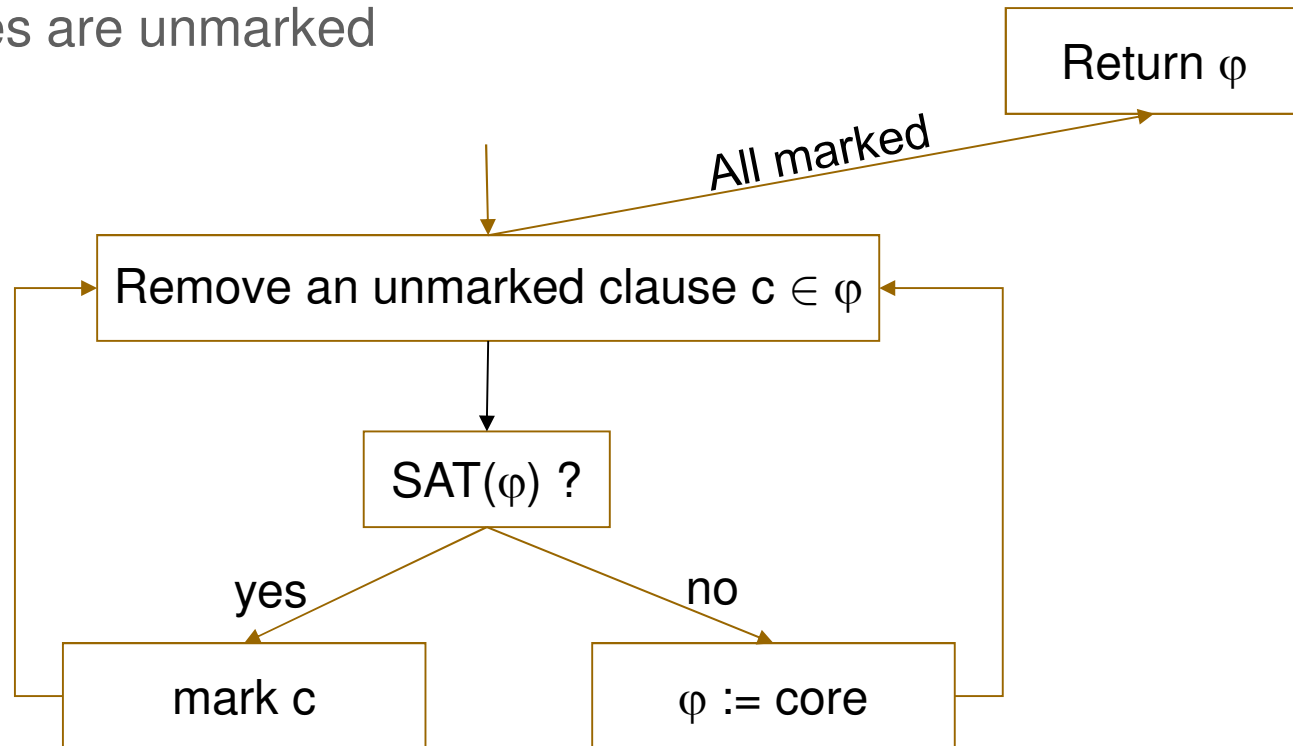
Core compression (smaller core)

- A basic approach: run until reaching a fixpoint [chaff]



Core compression (minimal core)

Initially φ 's clauses are unmarked



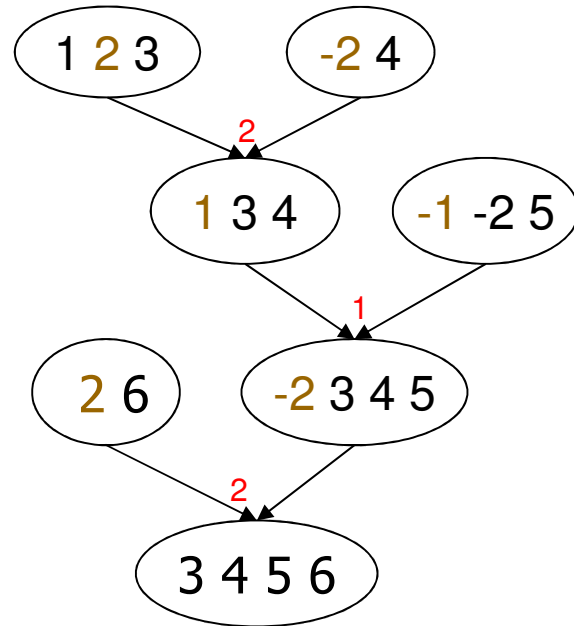
Proof-compression

linear-time transformation / “Recycle-pivots”

- Based on the following fact:
 - Every resolution proof can be made ‘regular’
 - ... which means that each pivot appears not more than once on every path.

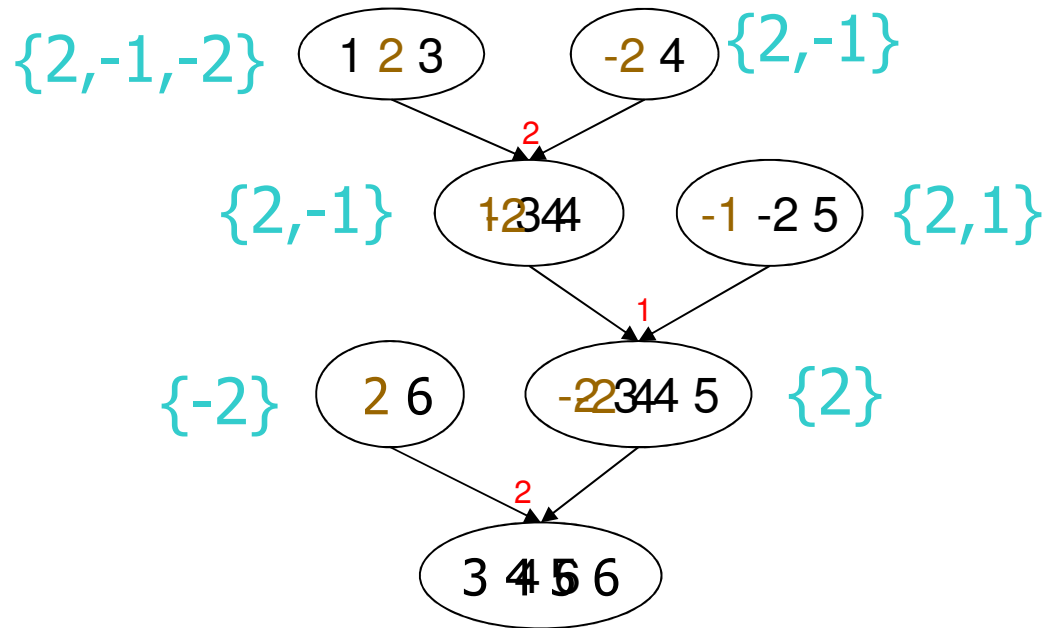
Proof-compression

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Proof-compression

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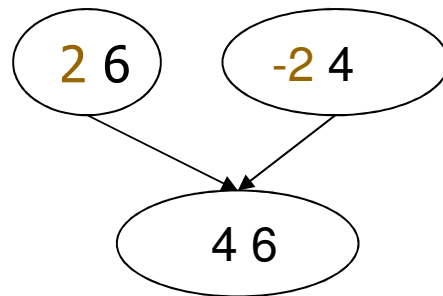


Reconstruct proof

Collect “removable literals”

Proof-compression

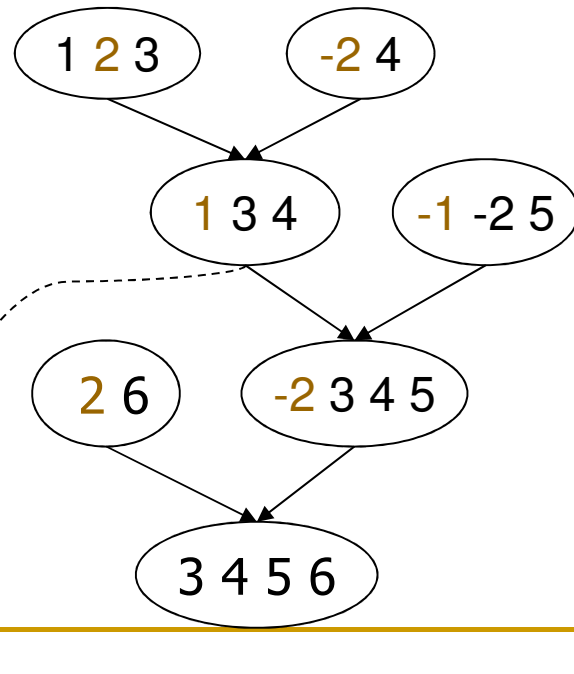
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Proof-compression

linear-time transformation / “Recycle-pivots”

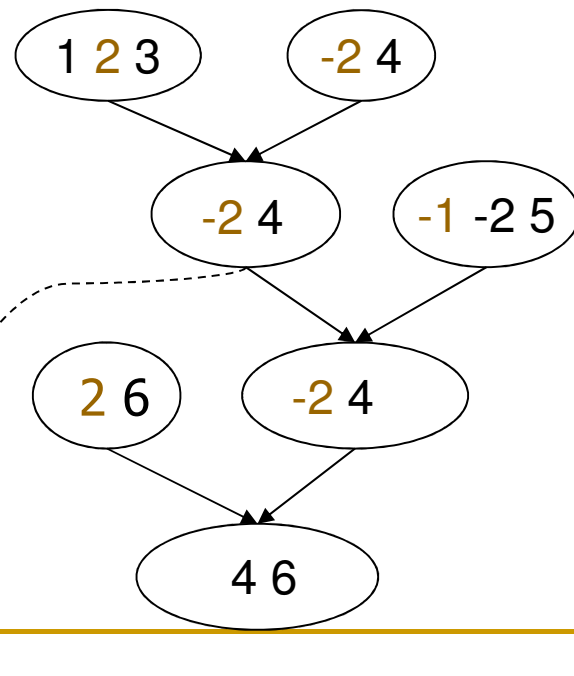
- Resolution graphs are DAGs
 - So, a node is on more than one path to the empty clause



Proof-compression

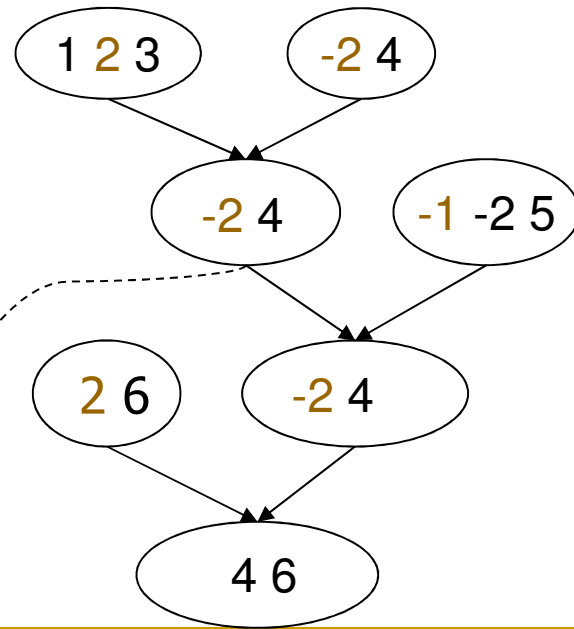
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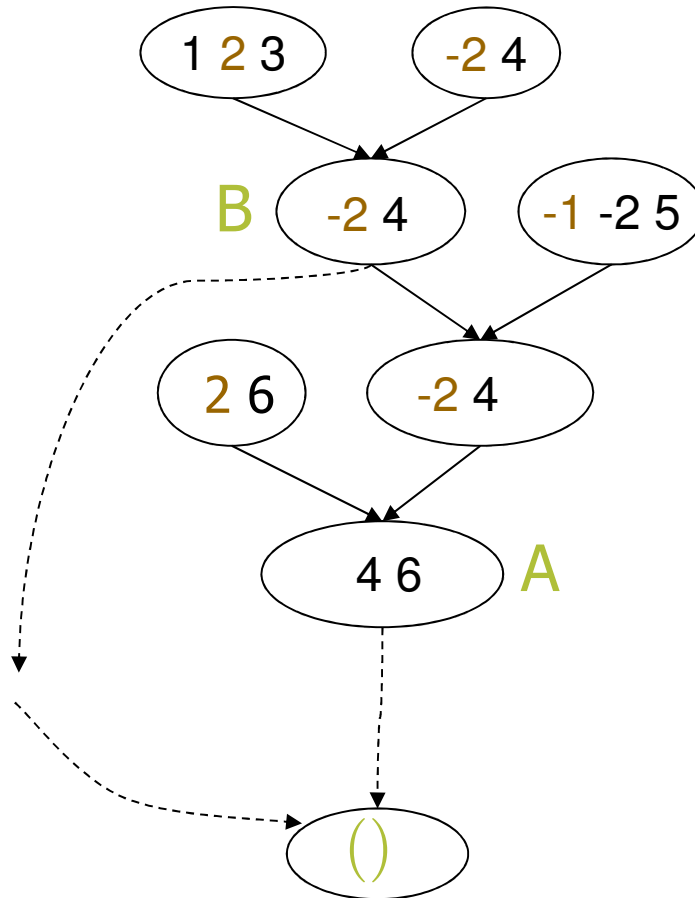
Proof-compression

linear-time transformation / “Recycle-pivots”



Proof-compression

linear-time transformation / “Recycle-pivots”



Does A dominate B ?

Dominance relation
can be found in
 $O(|E| \log |V|)$

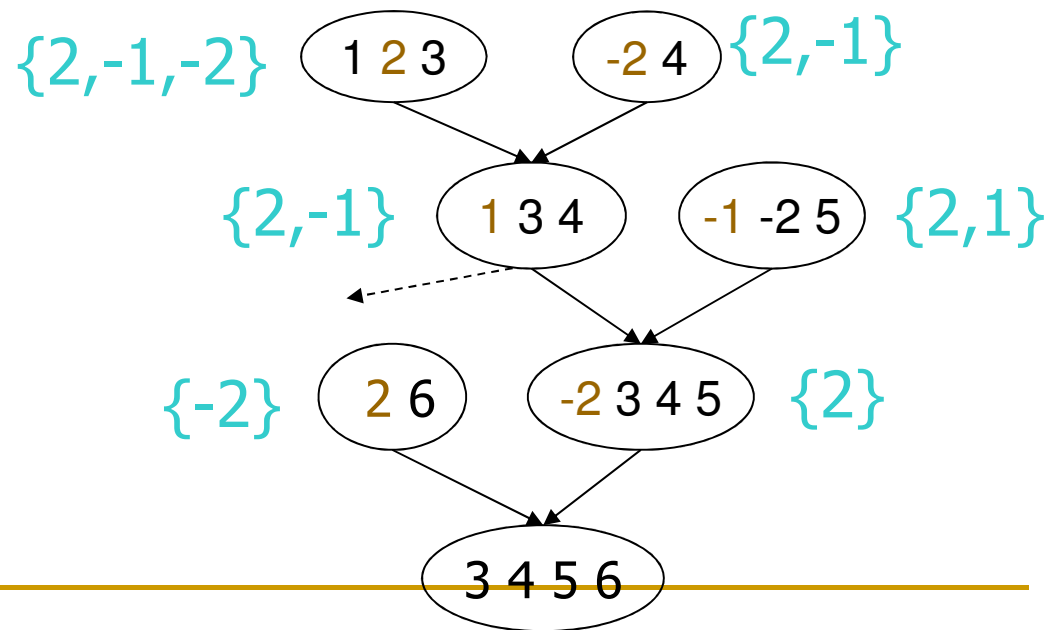
Problem: need to be
updated each time.

Proof-compression

linear-time transformation / “Recycle-pivots”

- Possible solution:

- Stop propagating information across nodes with more than one child.



Proof-compression

linear-time transformations / recent advances

■ Recycle pivots with intersection

- P. Fontaine, S. Merz and B. W. Paleo. *Compression of Propositional Resolution Proofs via Partial Regularization*. In CADE'11.

■ Local transformation Framework

- R. Bruttomesso, S.F. Rollini, N. Sharygina, and A. Tsitovich. *Flexible Interpolation with Local Proof Transformations*. In ICCAD'10.
- S.F. Rollini, R. Bruttomesso and N. Sharygina. *An Efficient and Flexible Approach to Resolution Proof Reduction*. In HVC'10.

■ Lower units

- P. Fontaine, S. Merz and B. W. Paleo. *Compression of Propositional Resolution Proofs via Partial Regularization*. In CADE'11.

■ Structural hashing

- S. Cotton. *Two Techniques for Minimizing Resolution Proofs*. In SAT'10.

All implemented in PeRIPLO by S. Rollini. Together they reduce the proof size by ~40%.

Summary

- SAT and CSP are not only about finding models
 - They can provide proofs
- Proofs are important for
 - validation
 - extracting cores
 - various formal-verification techniques
- Minimizing proofs/cores is a subject for intense research.

Questions ?