



# On the Characterization of **Until** as a **Fixed Point** under **Clocked Semantics**

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# In Singly Clocked Designs



- The signal that causes a memory element (flip-flop or latch) to make a transition is termed the **clock**
- The temporal operators in logics such as LTL are interpreted with respect to the **clock**.
- The formula

**globally** ( $p \rightarrow$  **next**  $q$ )

is interpreted as

**globally, if  $p$  then at the next clock tick,  $q$ .**



# In Multiply Clocked Designs



- Some flip-flops may be clocked with **clka** and some with **clkb**
  - Thus, the mapping between temporal operators and clock cycles cannot be done automatically
  - The formula itself must provide the desired mapping
- For example

globally (p -> next q)@clka

is interpreted as

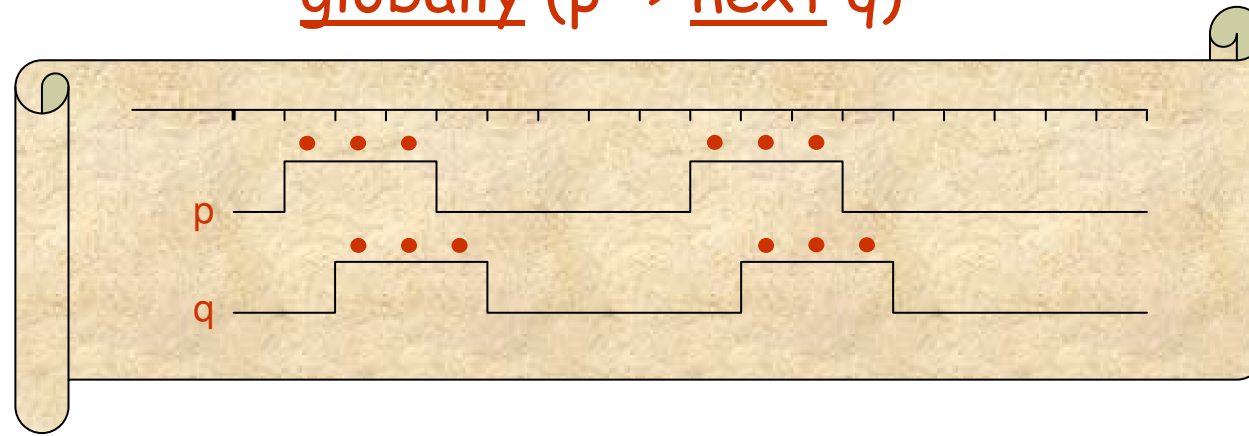
globally, if **p** during a cycle of **clka**  
then at the next clock tick of **clka**, **q**



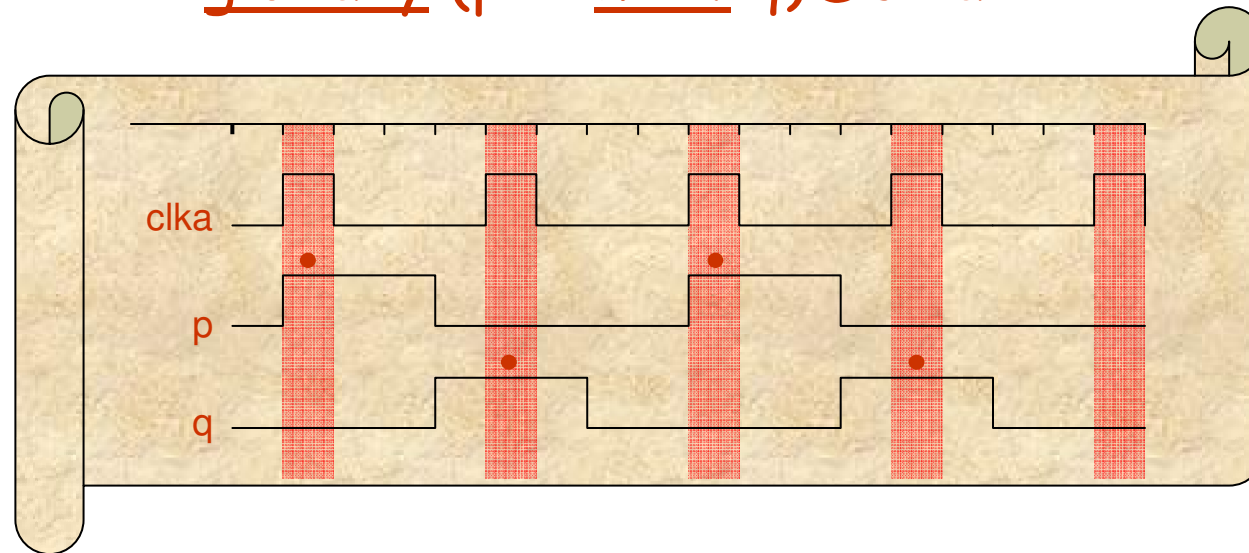
# Singly **vs.** Multiply Clocked Designs



globally (p -> next q)



globally (p -> next q)@clka





# Previous Work



- In [EFHMOV03] Eisner et al gave a simple semantics for LTL extended with a clock operator
- The suggested semantics has been adopted by the IEEE standards **PSL** and **SVA**
- The logic in [EFHMOV03] was measured against a list of design goals
- It was shown that it meets all design goals, **except for: preserving the least-fixed point characterization of the until! operator under multiple clocks**

The characterization of until as fixed point is not merely a theoretical issue  
- it has practical applicability for tools



# In this work

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- We show that with a minor addition to the semantics of [EFHMOV03] the **until!** operator **preserves** its least fixed-point characterization (as well as the other requirements)



# Overview of the talk

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- Understanding the ideas and semantics of [EFHMOV03]
- Understanding the problem with the least fixed-point characterization of until!
- The proposed solution



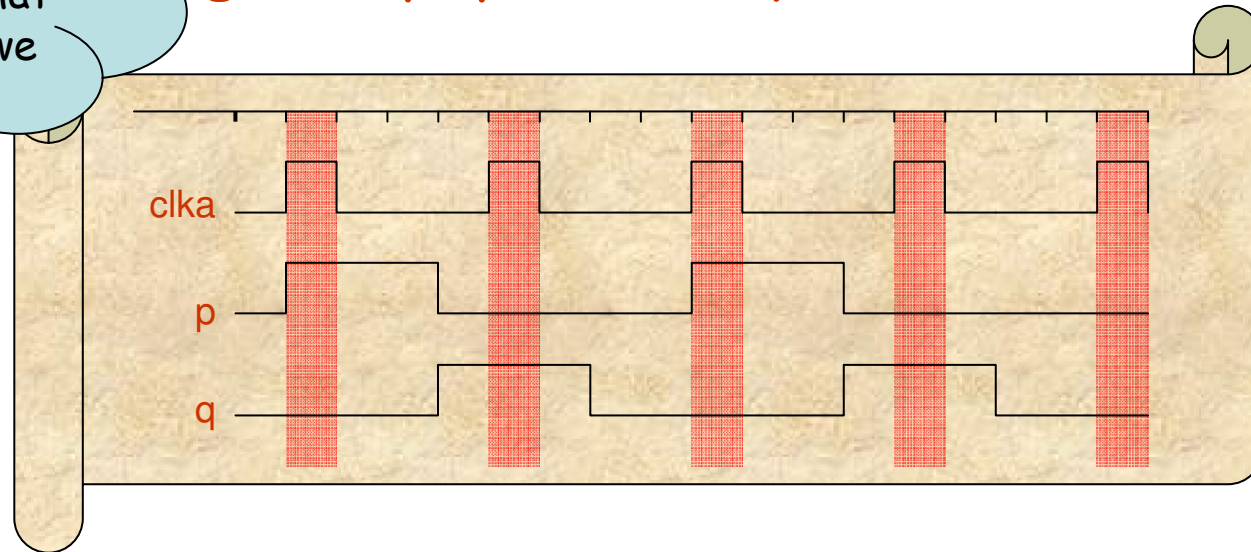
# The idea in [EFHMOV03]



- **Projection:** the role of the clock operator is to define the projection on the cycles in which the formula should be evaluated.

The projection is going to be one that we can **undo** (as we will see later)

globally (p  $\rightarrow$  next q)@clka



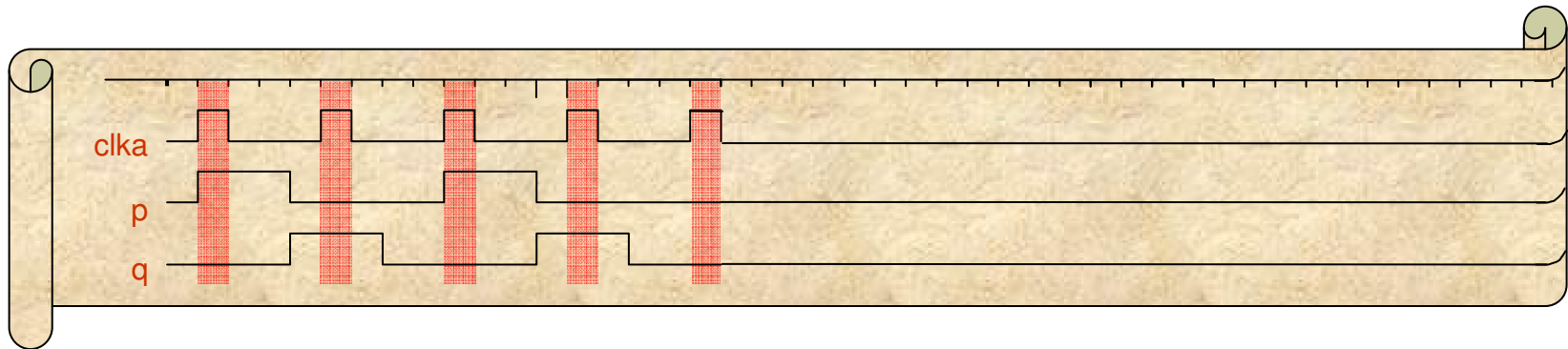




# Coping with finite ticks [EFHMOV03]



- But what if the clock **stops ticking**?
- The semantics of LTL is typically defined for **infinite** paths.
- A projection w.r.t **clka** of an **infinite** path where **clka** stops ticking yields a **finite** path

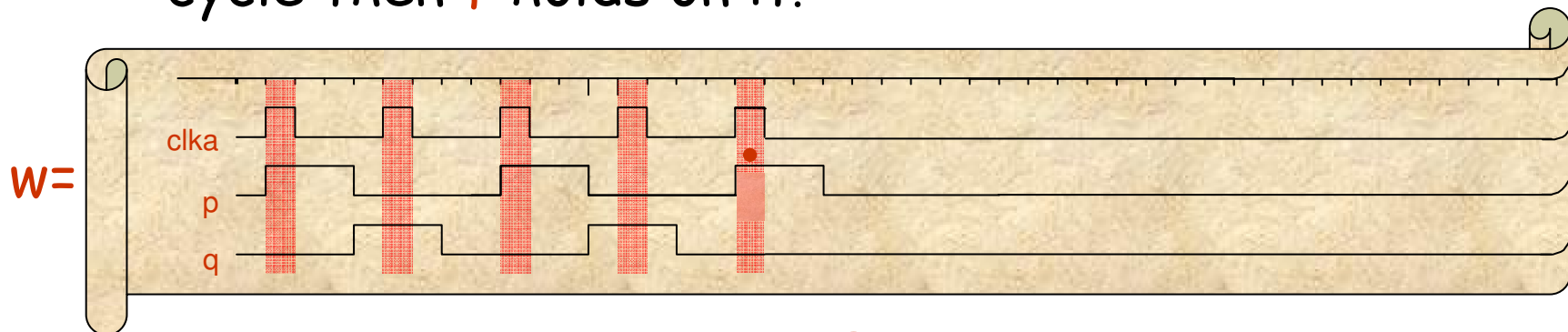




# Coping with finite ticks [EFHMOV3]



- **Solution:** use the **weak** and **strong** versions of the **next operator** (**next!** and **next**) that are introduced by Pnueli et al. for finite path
  - The formula **next! f** demands that there is a next cycle and **f** holds on it
  - Whereas **next f** demands that if there is a next cycle then **f** holds on it.



$w \not\models \text{globally } (p \rightarrow \text{next! } q) @ \text{clka}$

$w \models \text{globally } (p \rightarrow \text{next } q) @ \text{clka}$



# Coping with zero ticks [EFHMOV03]



- But what if the clock **never ticks**?
- The semantics of LTL (for finite/infinite words) assumes paths are non-empty.
- A projection w.r.t **clka** of a finite/infinite path where **clka** never ticks yields an **empty** path.



# Coping with zero ticks [EFHMOV03]



- Solution: define **weak** and **strong** versions of a boolean expression (**b!** and **b**)
- The formula **b!** demands that there is a **current cycle** and **b** holds on it
- Whereas **b** demands that if there is a **current cycle** then **b** holds on it.



# Nested Clocks [EFHMOV03]



- What happens in the event of a clock switch?
- Consider

$(\text{start} \rightarrow \underline{\text{next}} ((\text{busy} \underline{\text{until}} \text{end})) @ \text{clkb}) @ \text{clka}$

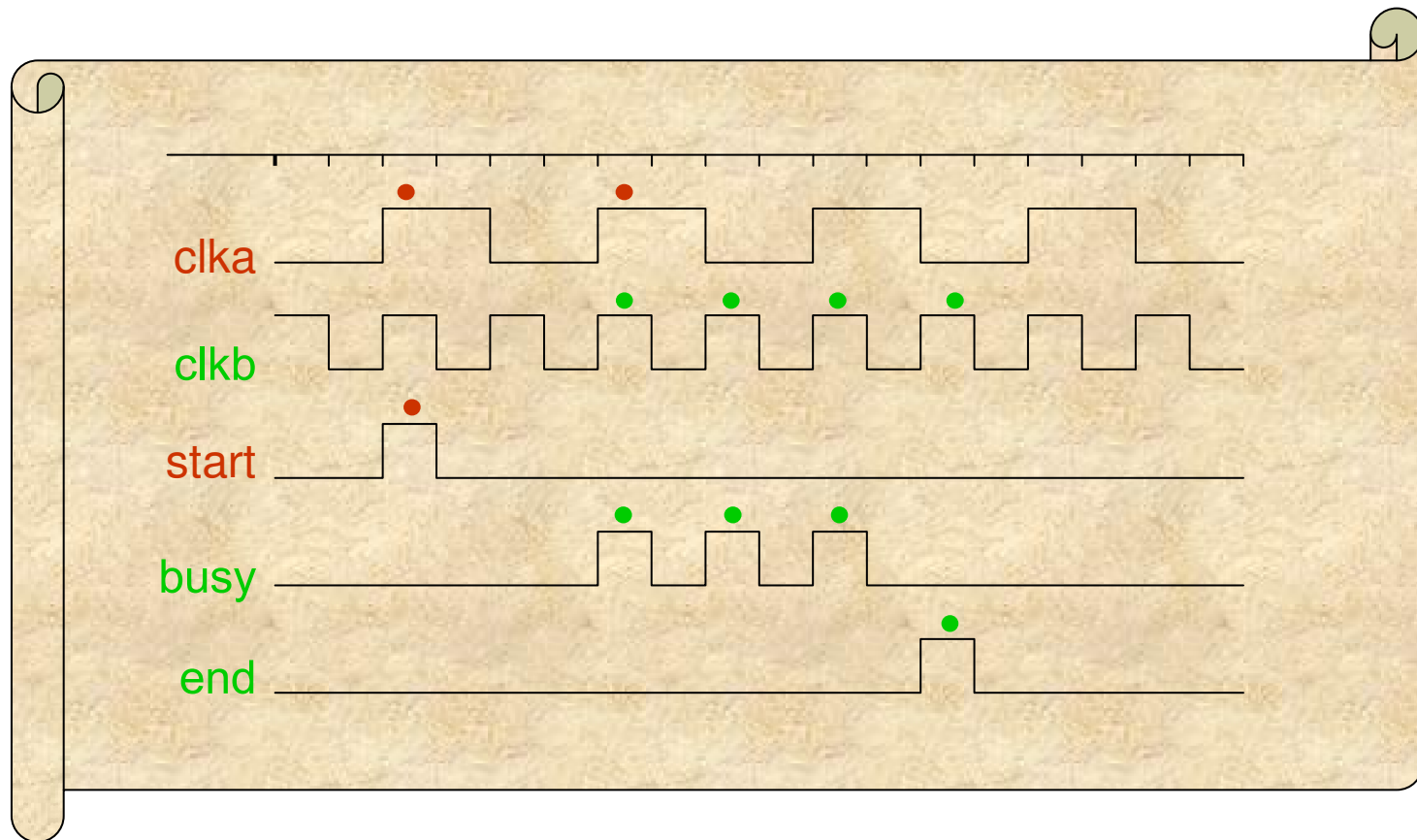
- We would like the **inner formula** to be evaluated on the cycle where **clkb** holds rather than the cycles where both **clka** and **clkb** hold
  - That is, we would like the **nested clock** to define a **new** projection rather than **refine** the projection further



# Nested Clocks [EFH MV03]



(start -> next ((busy until end))@clkb)@rose(clka)



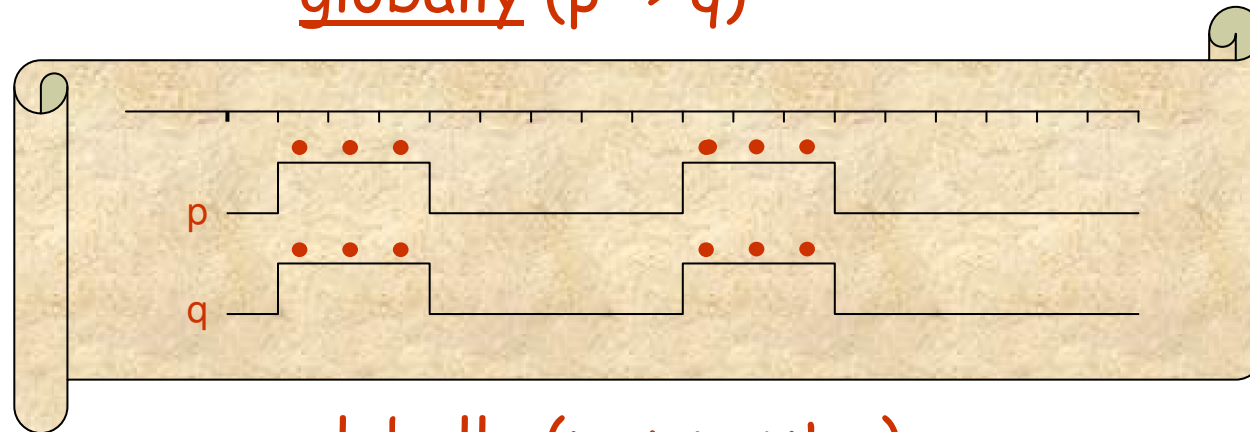


# $b$ and next $b$ under multiple clocks

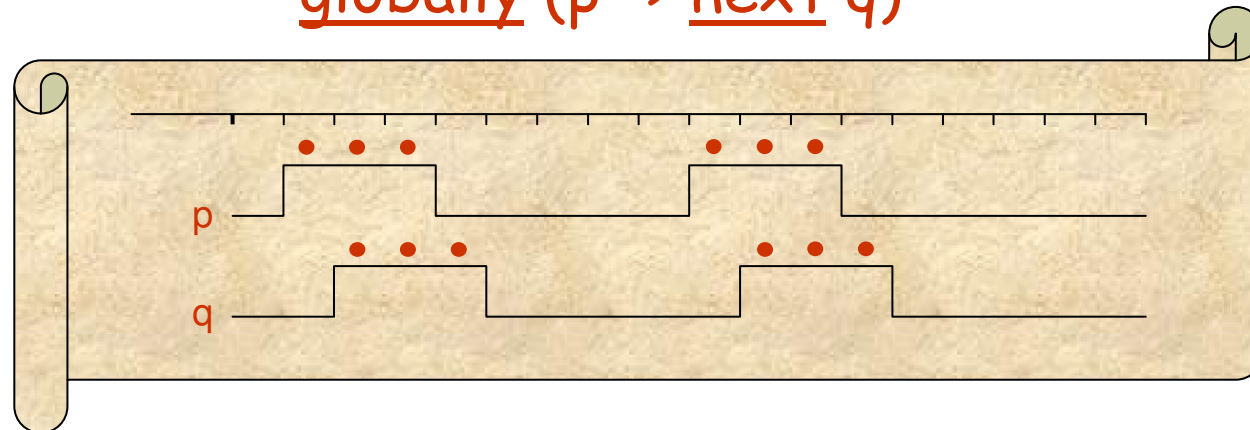


- In LTL
  - The formula  $b$  checks  $b$  at the **current** cycle
  - The formula next  $b$  checks  $b$  at the **next** cycle

globally ( $p \rightarrow q$ )



globally ( $p \rightarrow$  next  $q$ )





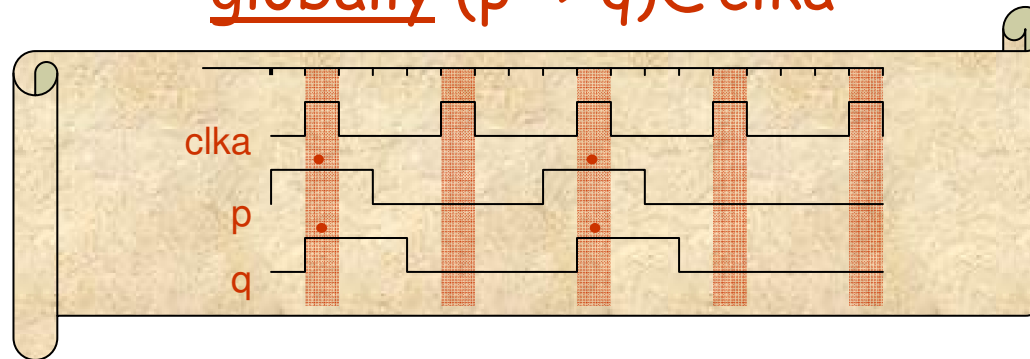
# $b$ and next $b$ under multiple clocks



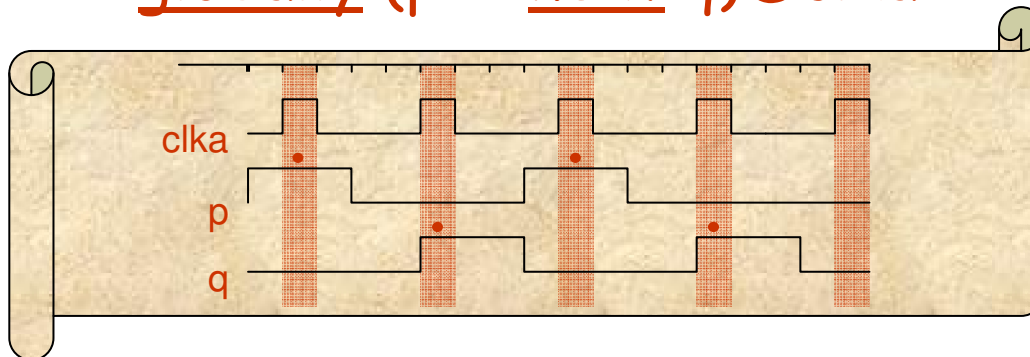
- In LTL@

- The formula  $b@clk$  checks  $b$  at the **closest** clock tick of  $clk$  (if such a tick exists)
- The formula next  $b@clk$  checks  $b$  at the **second closest** clock tick of  $clk$  (if such a tick exists)

globally  $(p \rightarrow q)@clka$



globally  $(p \rightarrow \text{next } q)@clka$





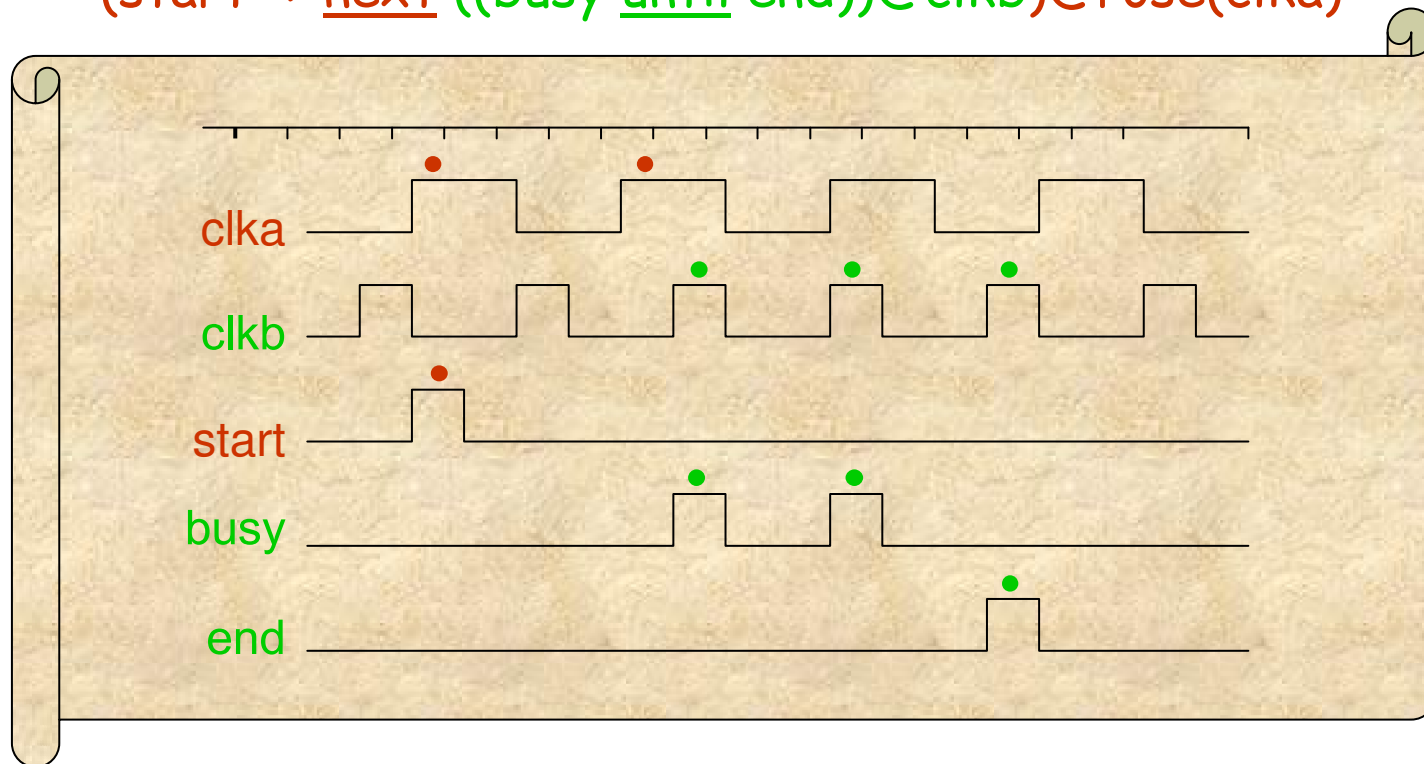


# Misaligned Nested Clocks



- In singly-clocked formulas all sub-formulas are **evaluated** on a **clock tick**, thus the **closest** clock tick is always the **current** tick
- In multiply-clocked formulas sometimes sub-formulas are **evaluated** on a cycle which is **not a clock tick**, thus the **closest** clock tick may be **different** than the **current** tick

(start -> next ((busy until end))@clkb)@rose(clka)





# The Semantics of [EFHMOV03]



A finite word  $w$  is a **clock tick** of  $clk$  if  $clk$  holds only on the last letter of  $w$ .

- $w \models_{clk} b!$  iff  $w$  contains at least **1** clock tick of  $clk$  and  $b$  holds on the first
- $w \models_{clk} b$  iff if  $w$  contains at least **1** clock tick of  $clk$  then  $b$  holds on the first
- $w \models_{clk} \text{next! } f$  iff  $w$  contains **2** clock ticks of  $clk$  and  $f$  holds on the second
- $w \models_{clk} \text{next } f$  iff if  $w$  contains **2** clock ticks of  $clk$  then  $b$  holds on the second
- $w \models_{clk} f \wedge g$  iff  $w \models_{clk} f$  and  $w \models_{clk} g$
- $w \models_{clk} \neg f$  iff  $w \not\models_{clk} f$
- $w \models_{clk} f \text{ until! } g$  iff there exists a clock tick of  $clk$  in  $w$  where  $g$  holds and  $f$  holds on every preceding tick of  $clk$
- $w \models_{clk} f \text{ until } g$  iff either  $w \models_{clk} f \text{ until! } g$  or  $f$  holds on every tick of  $clk$  in  $w$
- $w \models_{clk} f @ clk b$  iff  $w \models_{clk b} f$



# The Problem with [EFHMOV03]'s solution



- In LTL  $f$  until  $g$  is a least fixed-point solution of the equation

$$E(S) = g \vee (f \wedge \text{next! } S)$$

- In [EFHMOV03] Eisner et al show that  $f$  until  $g$  is a least fixed point solution of the equation

$$E'(S) = (\text{true!} \wedge g) \vee (f \wedge \text{next! } S)$$

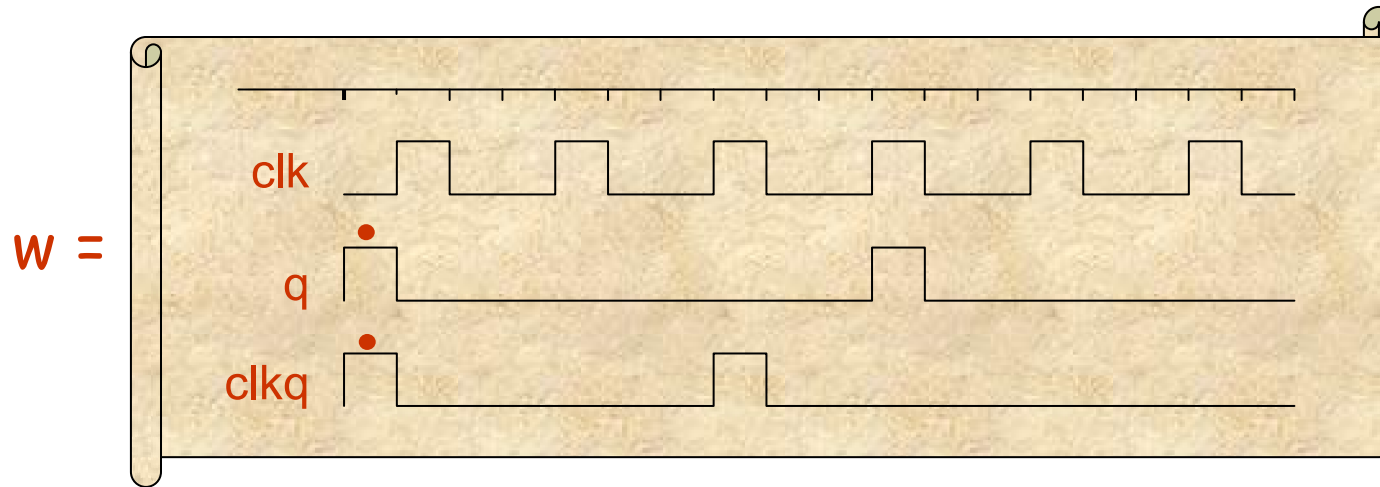
- If only a single clock is involved.
- When multiple clocks are involved the characterization no longer holds.



# The counter example [EFHMOV03]



$(p \text{ until! } (q @ clkq))$



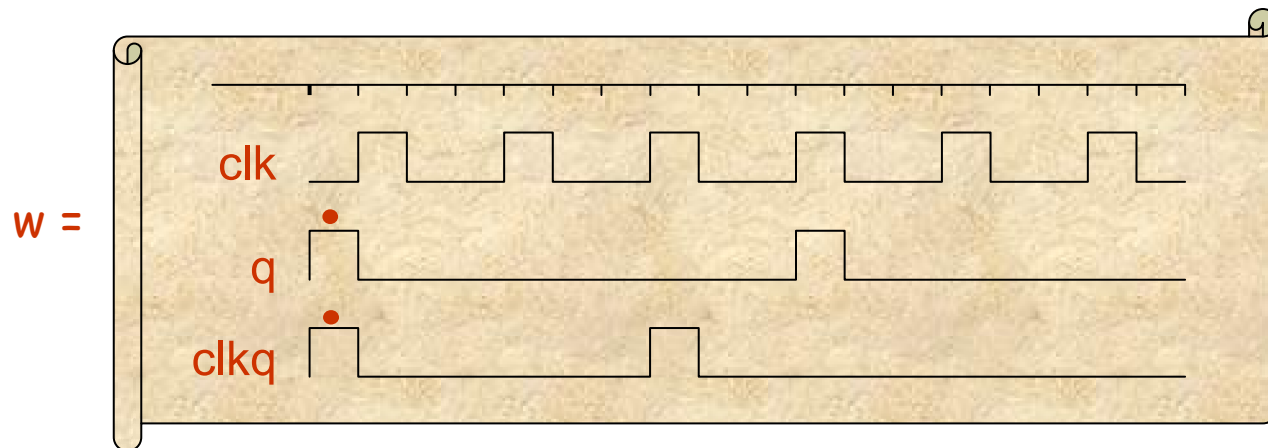
- $w \not\models_{clk} (p \text{ until! } (q @ clkq))$   
Since there is no clock tick of  $clk$  where  $q @ clkq$  holds
- $w \models_{clk} (true! \wedge (q @ clkq)) \vee (p \wedge Next! (p \text{ until! } (q @ clkq)))$   
Since both  $q @ clkq$  and  $true!$  hold on the first cycle



# The Problem



- The problem in [EFHMOV03] is that there is no way to express the property "evaluate  $f$  at the closest clock tick of  $clk_b$ "
  - Unless the clock context (the outer clock) is  $clk_b$
  - In the previous example we got that  $q@clk_q$  is evaluated **now** while we wanted it to be evaluated at the **closest clock tick** of  $clk$



$$w \models_{clk} (q@clkq)$$



# Solution

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- **Solution:** introduce an **alignment operator** (such as in **CBV**) that takes you to the closest clock tick
  - Actually 2 alignment operators (weak & strong)



# Formally



- We introduce next!<sup>m</sup> and next<sup>m</sup>
  - The formula (next!<sup>m</sup> f)@clk demands there are m+1 clock ticks of clk and f holds on the last of them
  - The formula (next<sup>m</sup> f)@clk demands that if there are m+1 clock ticks of clk then f holds on the last of them
- When the exponent
  - m=1 we get the usual next/next! operators
  - m>1 we get iteration of the usual next/next! operators
  - m=0 we get the alignment operators



# The Semantics of [EFHMOV03]



A finite word  $w$  is a **clock tick** of  $clk$  if  $clk$  holds only on the last letter of  $w$ .

- $w \models_{clk} b!$  iff  $w$  contains at least 1 clock tick of  $clk$  and  $b$  holds on the first
- $w \models_{clk} b$  iff if  $w$  contains at least 1 clock tick of  $clk$  and  $b$  holds on the first
- $w \models_{clk} \underline{next!} f$  iff  $w$  contains 2 clock ticks of  $clk$  and  $f$  holds on the second
- $w \models_{clk} \underline{next} f$  iff if  $w$  contains 2 clock ticks of  $clk$  then  $b$  holds on the second
- $w \models_{clk} f \wedge g$  iff  $w \models_{clk} f$  and  $w \models_{clk} g$
- $w \models_{clk} \neg f$  iff  $w \not\models_{clk} f$
- $w \models_{clk} f \underline{until!} g$  iff there exists a clock tick of  $clk$  in  $w$  where  $g$  holds and  $f$  holds on every preceding tick of  $clk$
- $w \models_{clk} f \underline{until} g$  iff either  $w \models_{clk} f \underline{until!} g$  or  $f$  holds on every tick of  $clk$  in  $w$
- $w \models_{clk} f @ clk b$  iff  $w \models_{clk b} f$





# The Resulting Semantics



A finite word  $w$  is a **clock tick** of  $clk$  if  $clk$  holds only on the last letter of  $w$ .

- $w \models_{clk} b!$  iff  $w$  contains at least 1 clock tick of  $clk$  and  $b$  holds on the first
- $w \models_{clk} b$  iff if  $w$  contains at least 1 clock tick of  $clk$  and  $b$  holds on the first
- $w \models_{clk} \text{next!}^m f$  iff  $w$  contains  $m+1$  clock ticks of  $clk$  and  $f$  holds on the second
- $w \models_{clk} \text{next}^m f$  iff if  $w$  contains  $m+1$  clock ticks of  $clk$  then  $b$  holds on the second
- $w \models_{clk} f \wedge g$  iff  $w \models_{clk} f$  and  $w \models_{clk} g$
- $w \models_{clk} \neg f$  iff  $w \not\models_{clk} f$
- $w \models_{clk} f \text{ until! } g$  iff there exists a clock tick of  $clk$  in  $w$  where  $g$  holds and  $f$  holds on every preceding tick of  $clk$
- $w \models_{clk} f \text{ until } g$  iff either  $w \models_{clk} f \text{ until! } g$  or  $f$  holds on every tick of  $clk$  in  $w$
- $w \models_{clk} f @ clk b$  iff  $w \models_{clk b} f$



# Fixed-Point Characterization of until!



- In LTL  $f$  until!  $g$  is a least fixed-point solution of the equation

$$E(S) = g \vee (f \wedge \text{next! } S)$$

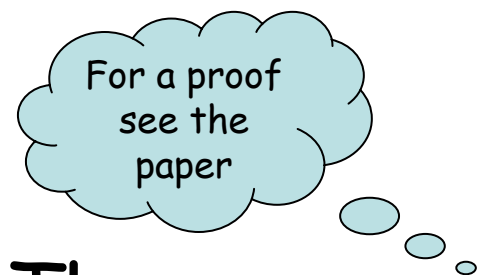
- In the suggested logic  $f$  until!  $g$  is a least fixed point solution of the equation

$$E'(S) = \text{next!}^0 (g \vee (f \wedge \text{next! } S))$$

- That is

$$E'(S) = \text{next!}^0 E(S)$$

- A simple generalization of the LTL characterization!!!



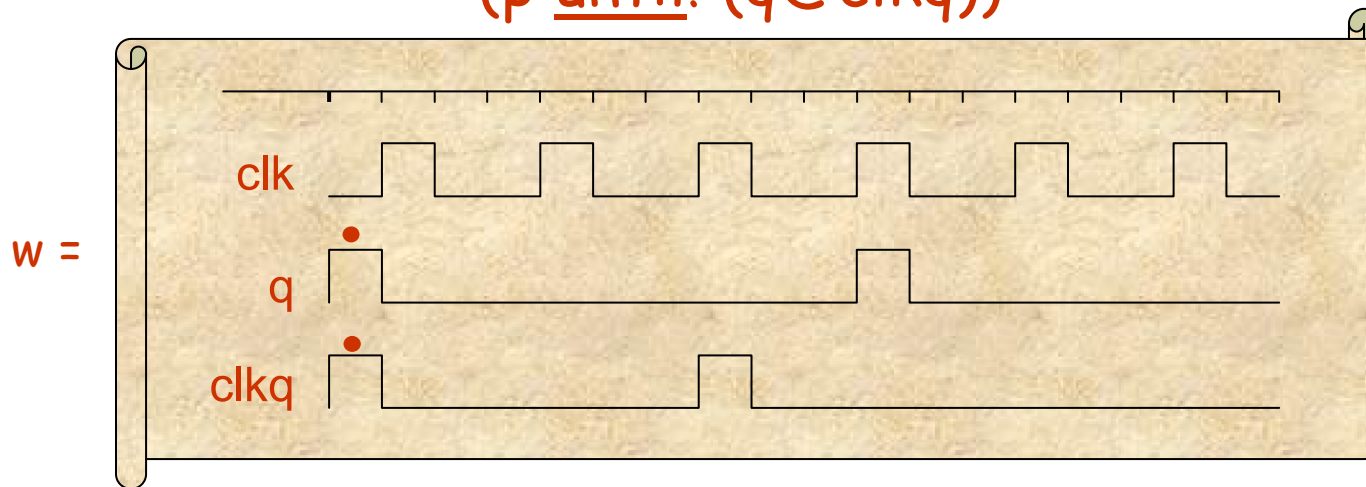


# Examining that counter example



- The problem with the counter example was that the until formula did not hold while the "bad" fixed-point characterization did.
- Now both do not hold:

$(p \text{ until! } (q@clkq))$



$w \not\models_{clk} \text{next!}^0 ((q@clkq) \vee (p \wedge \text{next!} (p \text{ until! } (q@clkq))))$

since both  $w \not\models_{clk} \text{next!}^0 (q@clkq)$

and  $w \not\models_{clk} \text{next!}^0 \text{next!} (p \text{ until! } (q@clkq))$



# Conclusions



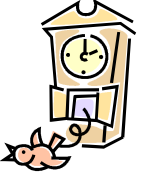
- We have shown that by adding weak/strong alignment operators to  $LTL^@$  the least fixed-point characterization of until! is preserved
- The resulting logic is obtained by augmenting the next/next! operators of  $LTL^@$  by an exponent
  - the alignments operators are obtained by taking the exponent to be zero
- The resulting semantics meets all other requirements set by [EFHMOV03]

For proofs  
see the  
paper



# The End

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# Thank you!