

Using Virtual Coverage to Hit Hard-to-Reach Events

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Prelude

- Bug in a complex multiprocessor system found in the lab
 - Overflow (that was not supposed to happen) in an internal buffer caused the system to hang
- Attempts to recreate the bug in simulation failed
 - The necessary conditions for the bug were identified
 - But even reaching them in simulation was difficult
- Even so, the bug was fixed and the bug fix is (apparently) correct
- Still, the design and verification teams want reassurance that the bug does not exist in current and future versions
- ... and here we enter the picture

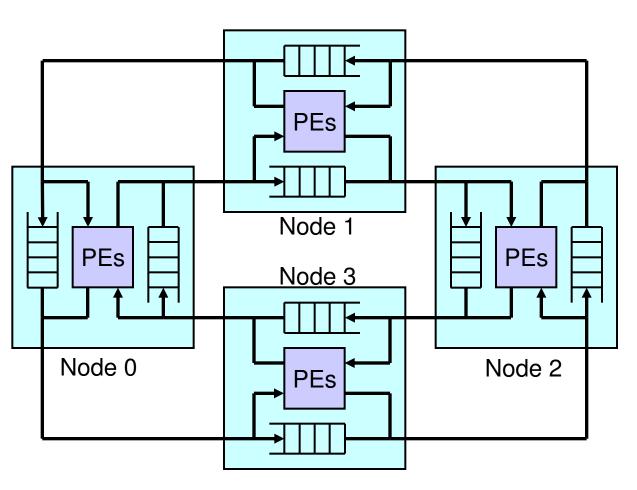


Outline

- ♦ The problem
 - Description of the target system
 - Description of the coverage goal (bug)
 - Manual solution
- Coverage Directed Generation
 - Concept of operation
 - Where and why it works
 - Why it does not work in our case
- ♦ Virtual coverage
 - What it is
 - Using it in our case
 - Results
- Summary and conclusions



The Target System

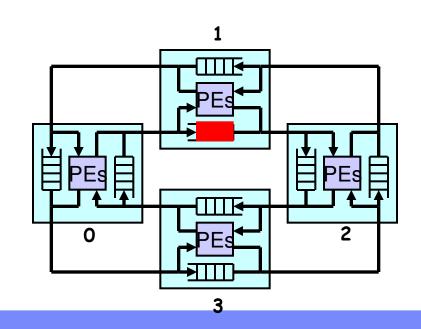


- ♦ Four compute nodes
 - 8 processors
 - ♦ I/O
 - Memory
 - Caches
- Two unidirectional rings for communication
 - Used mostly for accessing memory on remote nodes
- Small flow-through buffers for transient transactions
- Two modes of operation
 - Closed ring
 - Open ring



The Coverage Goal

- The bug caused an overflow in one of the flow-through buffers, which in turn caused the system to hang
- Necessary condition for the bug: The flow-through buffer is full for long periods of time
- The target coverage event: Fill a specific flow-through buffer for more than 50 cycles

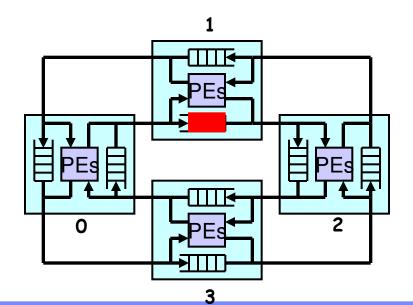




Manual Solution

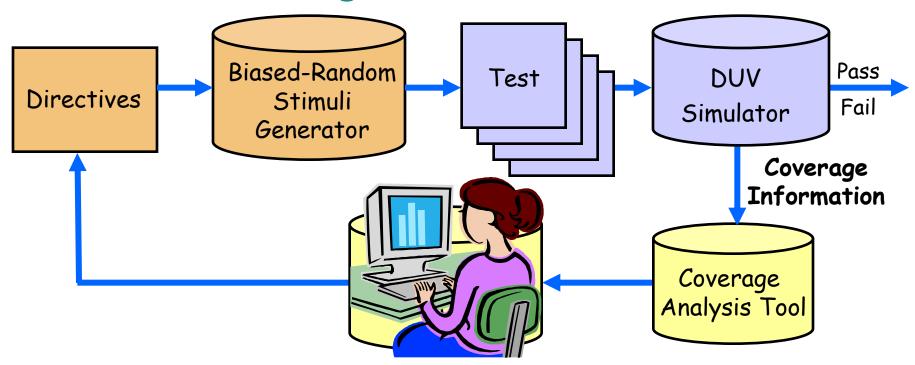
- Work in open ring mode
 - Increase traffic using relevant buffer
- © Create directive files with parameters that lead toward the target
 - More transactions using the buffer
 - Push from Node 0, pull from Node 2
 - Processor and I/O transactions
 - Many types
 - Cause transactions to stay longer
- Simulate the system with the directive files
- Analyze the results
 - If target not reached, repeat

But CDG can automatically reach coverage events





Data-Driven Coverage Directed Generation



- Reduce the bottleneck of closing the loop from coverage to generation
- Replace human expert with automatic reasoning
- Leads to faster and better coverage with fewer resources



How Data-Driven CDG Works

- The CDG engine is fed pairs of inputs (directives) and outputs (coverage data)
 - These pairs are often called training data
- The CDG engine "understands" the relations between inputs and outputs and can answer queries about the relations
 - What directive can lead to a requested coverage event?
- ♦ Two levels of understanding
 - Memorizing
 - ♦ Generalization
- In CDG we are usually interested in pairs not seen in the training data
 - Specifically, how to reach uncovered events
- → Generalization is the key to success



How to Generalize

- Need to know the relations between items in the output space
 - And similarly in the input space

♦ Example - ordering rules (<, >, =)



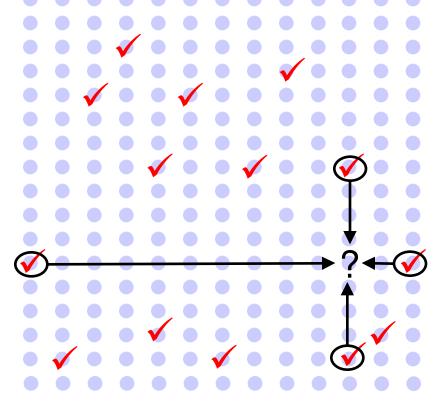
- ♦ Example similarity
 - Usually means breaking the item into sub-items





Cross-Product Coverage and Generalization

- Cross-product coverage is a natural form for generalization in the coverage space
 - Break up the output space along the attribute's axis
 - Understand the input-output relations for each attribute
 - Generalize by combining the understandings
- But life is not that simple
 - Attributes are related
 - Conflicting understanding
 - Randomness
 - **...**





Back to the Flow-Through



But how can CDG generalize from a singular event?

CDG can automatically reach coverage events

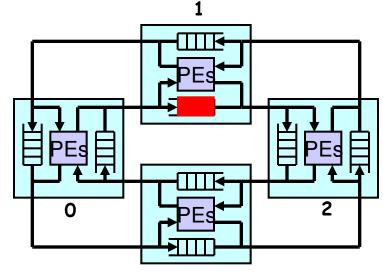
So build a structured coverage model around it and use this model to generalize



Virtual coverage model is a structured coverage model defined around the target coverage event

- The target event is one of the points in the virtual coverage model
- The model is defined to help CDG exploit its structure to learn how to reach the target event

Covering the virtual model is not a goal of the verification plan



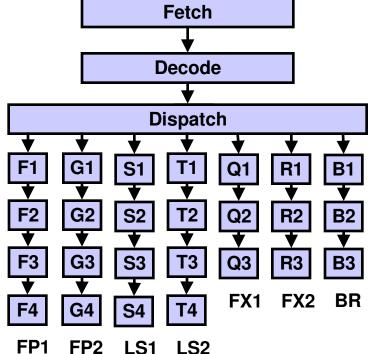


How to Define a Virtual Coverage Model

- Break the target event into a set of sub-events
 - The sub-events can be implicit
 - Dependency between the sub-events is possible

Each sub-event is an attribute in a cross-product model with its own set of possible values
Fetch

Dispatch is blocked from below ⇔
cannot dispatch to F1 and cannot dispatch to G1 and
... and cannot dispatch to B1 ⇒
Dispatch to F1 (Y/N) N
Dispatch to G1 (Y/N) N
...
Dispatch to B1 (Y/N) N





How to Define a Virtual Coverage Model (II)

- Augment the basic virtual model with additional information
 - Add values to attributes representing sub-events
 - New attributes that do not directly belong to the target event
- Augmenting the model increases its size

```
Dispatch is blocked from below ⇒

State of F1 (free, busy, on hold, ...) on hold

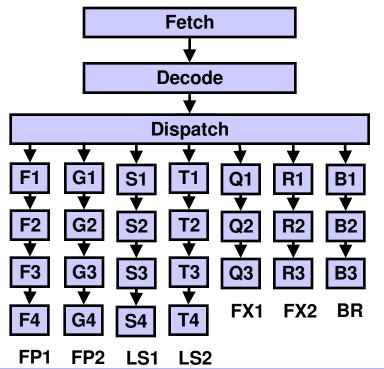
...

State of B1 (free, busy, on hold, ...) on hold

State of F2 (free, executing, finished)

...

State of B2 (free, executing, finished)
```





Virtual Coverage and the Flow-Through Buffer

- The target event is to fill the flow-through buffer and keep it full for more than 50 cycles
- ♦ The basic virtual coverage model
 - ♦ Flow-through buffer full (Y/N) Y
 - More than 50 cycles from arrival to next departure (Y/N) Y
- After adding values to the attributes
 - ♦ Flow-through buffer utilization (0, 1, 2, ..., 7, 8) 8
 - ♦ Time from arrival to next departure (0-10, 11-20, ..., 50-100, 100-) 50-100 and 100-
- Adding new attributes
 - Time in buffer
 - Arrival rate
 - Transaction command



CDG and the Virtual Coverage Model

- Identify relevant parameters in the test generator directive files
 - Start with parameters identified by a domain expert
 - Use sensitivity analysis to ensure that the parameters are relevant and which coverage attributes they influence
- Identified parameters included
 - CPU initiated transactions
 - ♦ Instruction fetch, data fetch, data store
 - ♦ I/O initiated transactions
 - Data read and write
 - Addresses of transactions



CDG and the Virtual Coverage Model (II)

- Suild the CDG engine for the specific virtual coverage model and relevant parameters
 - ♦ In our case, the CDG engine is based on Bayesian Networks
 - Building the CDG engine comprised
 - Manual definition of the Bayesian Network structure
 - Automatic training of the network
- Use the CDG engine to generate directives file with highest probability of reaching the target event



CDG Results

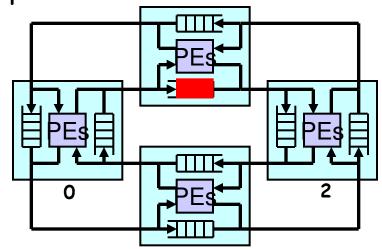
- We reached the target event ... and more
 - Buffer remains full for very long periods of time
 - Works in both open and closed ring modes
 - With better results in the open ring mode
 - Good control of the transactions that fill the buffer

	Open ring mode	Close ring mode
Probability of reaching the event	50%	30%
Maximal full time	200 cycles	140 cycles



Analysis of Results

- ♦ In general, no big surprises
 - Node 0 pushes data to Node 2
 - Node 2 pulls data from Node 0
 - Node 1 utilizes the ring
- ♦ CDG is better than manual directive files because
 - Node 1 utilization of the ring is very important
 - CPU transactions are more important than believed
 - Fine tuning the mix of transaction sources and types





Flow-Through Buffer Summary

- We reached the target event ... and more
- 13 Overall effort three person months, four calendar months
 - This effort is much too high for "normal" coverage events
- 12 We did not find any bug during that process
 - But apparently, there are no related bugs in the design
 - We did not try our solution on the buggy design
- We increased the confidence of the design and verification teams that such a bug does not exist



Conclusions

"The paper gives the impression that this was a somewhat ad-hoc approach where a specific example drove the work and afterwards a paper got written around it."



- ♦ Started with two ideas for solutions to a difficult problem
 - Use CDG to reach a hard-to-reach coverage event
 - Learn how to reach the event by building a grid of events around it
- Built a concept around it
 - Gave it a catchy name "virtual coverage"
 - Some guidelines on how to define the coverage model
 - Identified strength and weakness in concept
- Working to address weaknesses
 - Reduce effort by increased automation in virtual coverage definition



Increased Automation in Virtual Coverage Definition

Syntactically break the target event into sub-events based on state variables in cone-of-influence

Each variable is an attribute

in the virtual model

Initial experiments show promising results

