

Using Constraint Satisfaction Formulation and Solution Techniques for Random Test Program Generation

Roy Emek

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IBM Research Lab in Haifa

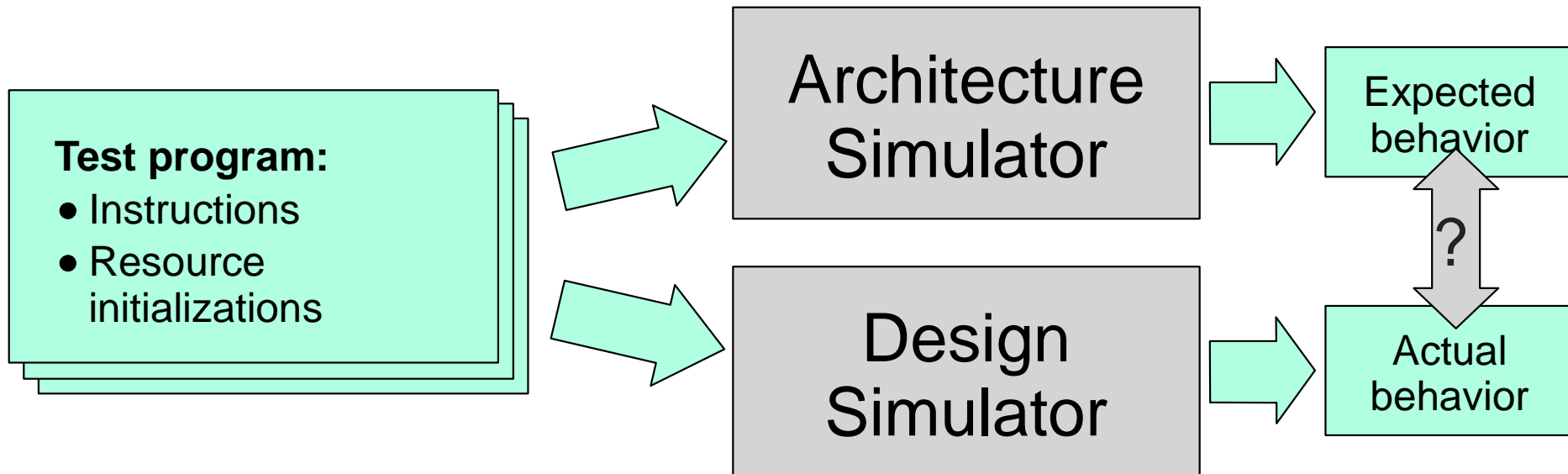


- **Random test program generation**
- **Constraint Satisfaction Problems (CSP)**
- **Modeling test programs as CSP**
- **CSP for random test generation:
characteristics**
- **Solution building blocks**

[Based on a paper by E. Bin,
R. Emek, G. Shurek and A. Ziv]

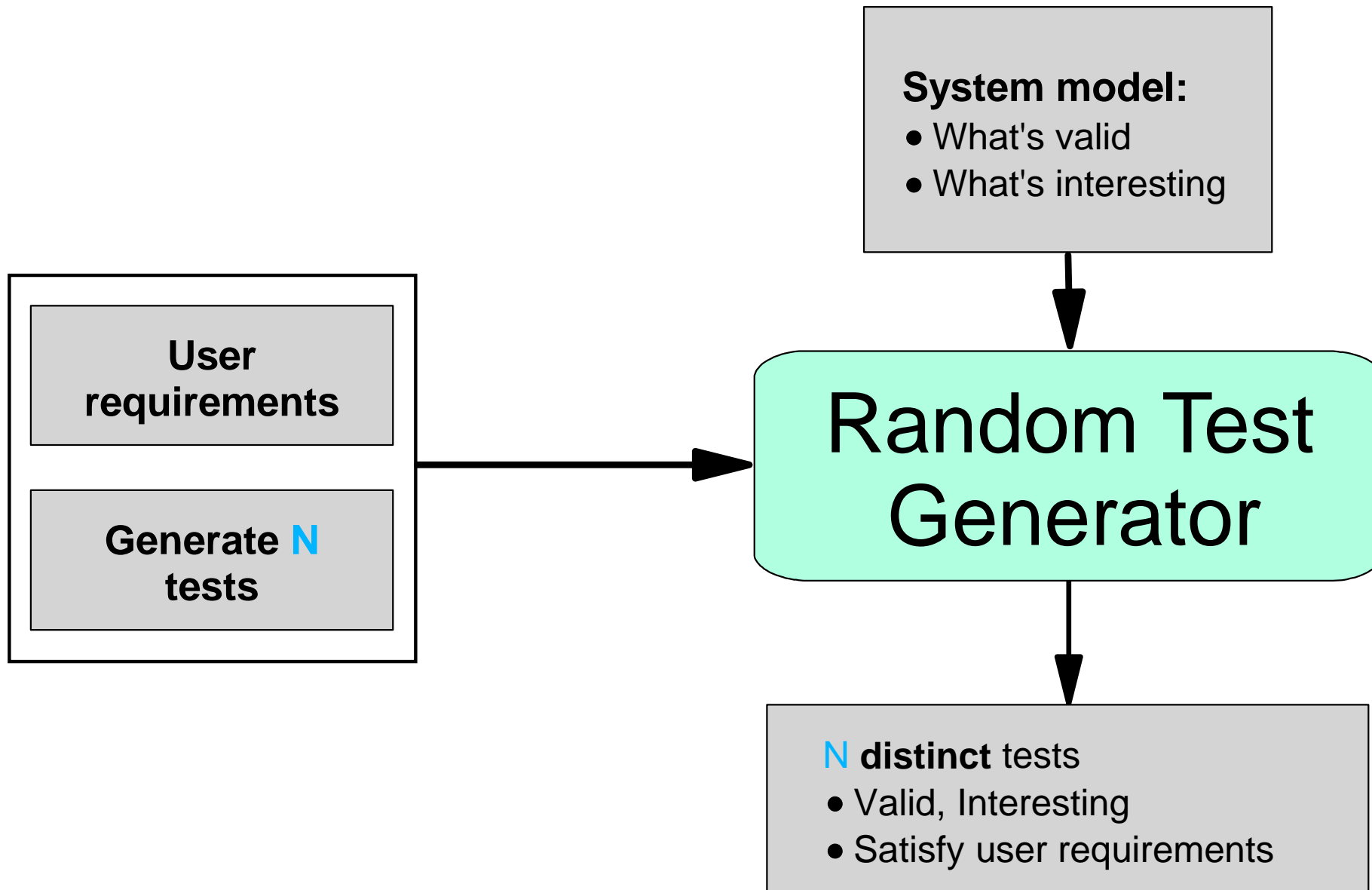


Verification Through Simulation





Random Test Program Generator



Test Program Constraints

Test quality: sum
overflow

```
add R1 ← R2 + R3
load Rx ← 1000 (Ry)
???? ??, Rz
mult Rz ← R6 × R7
```

Validity: $x \neq y$

User request: same register



CSP Definition

[Mackworth, Freuder, Montanari, Dechter, Rossi, ...]

- **Variables** of the problem
 - address, register_value
- **Domain (set)** for each variable
 - address: 0x0000 - 0xFFFF
 - number of bytes in a 'load': { 1, 2, 4, 8, 16 }
- **Constraints (relations)** over variables
 - (load n bytes) \Rightarrow (align address to n bytes boundary)
 - $\text{value}(\text{base_reg}) + \text{displacement} = \text{address}$

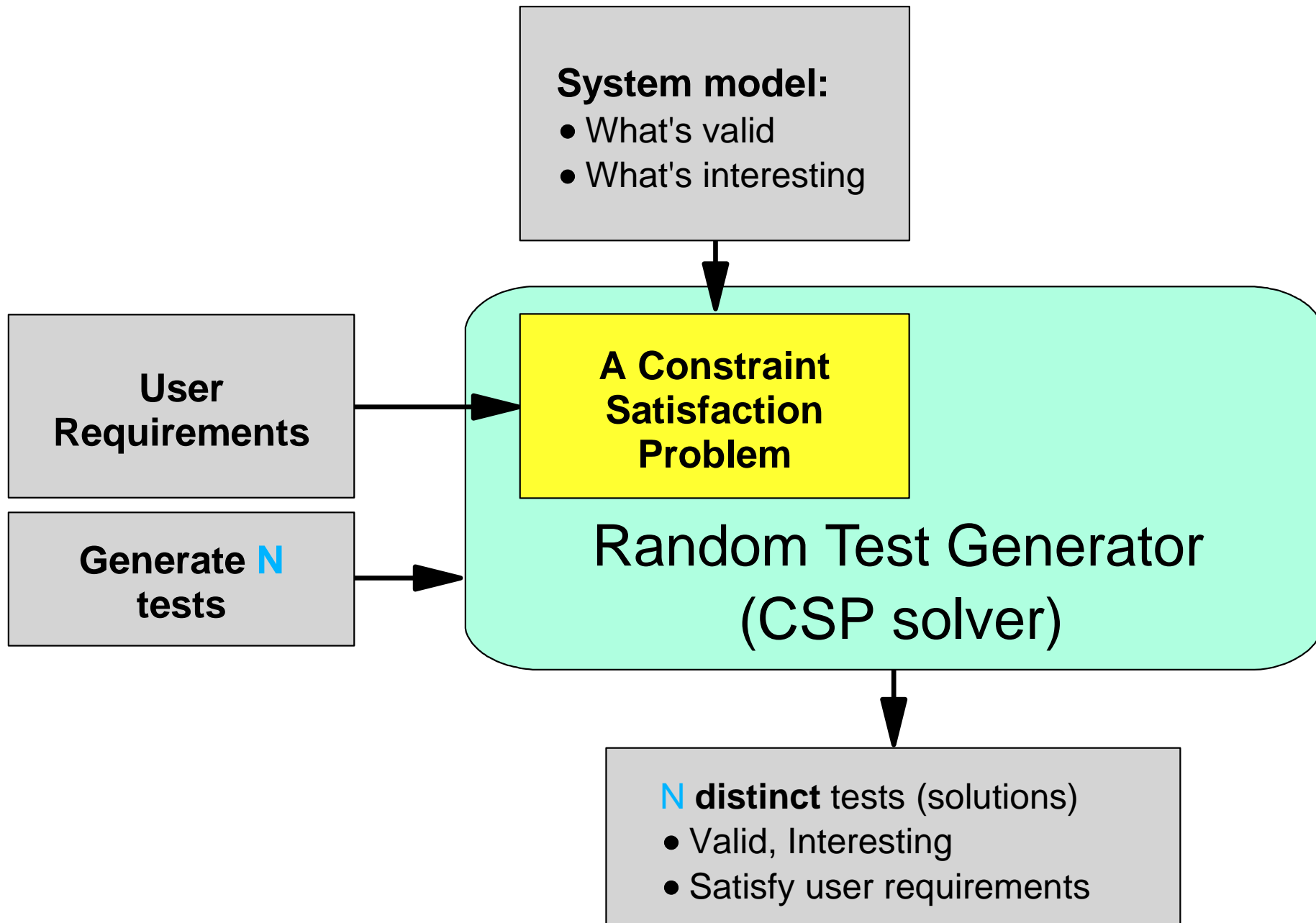


CSP Definition (cont)

- **Solution for a CSP**
 - Every variable is assigned a value from its domain
 - The assignments satisfy all the constraints
- **Example**
 - Variables: a, b, c
 - Domains:
 - $A = \{1,2,3\}$; $B = \{2,3,4,5\}$; $C = \{1,3,5\}$
 - Constraints:
 - $a^2 < b$; $c \neq b$; $a < c - 1$
 - Solution:
 - $a = 1$; $b = 4$; $c = 3$



Random Test Program Generator (2)





CSP@RTG Characteristics

- **Random, uniform distribution solution**

[Yuan et al. '99, Dechter et al. '02]

- As opposed to one, all, or 'best' solution

- **Huge domains: 2^{64} and more**

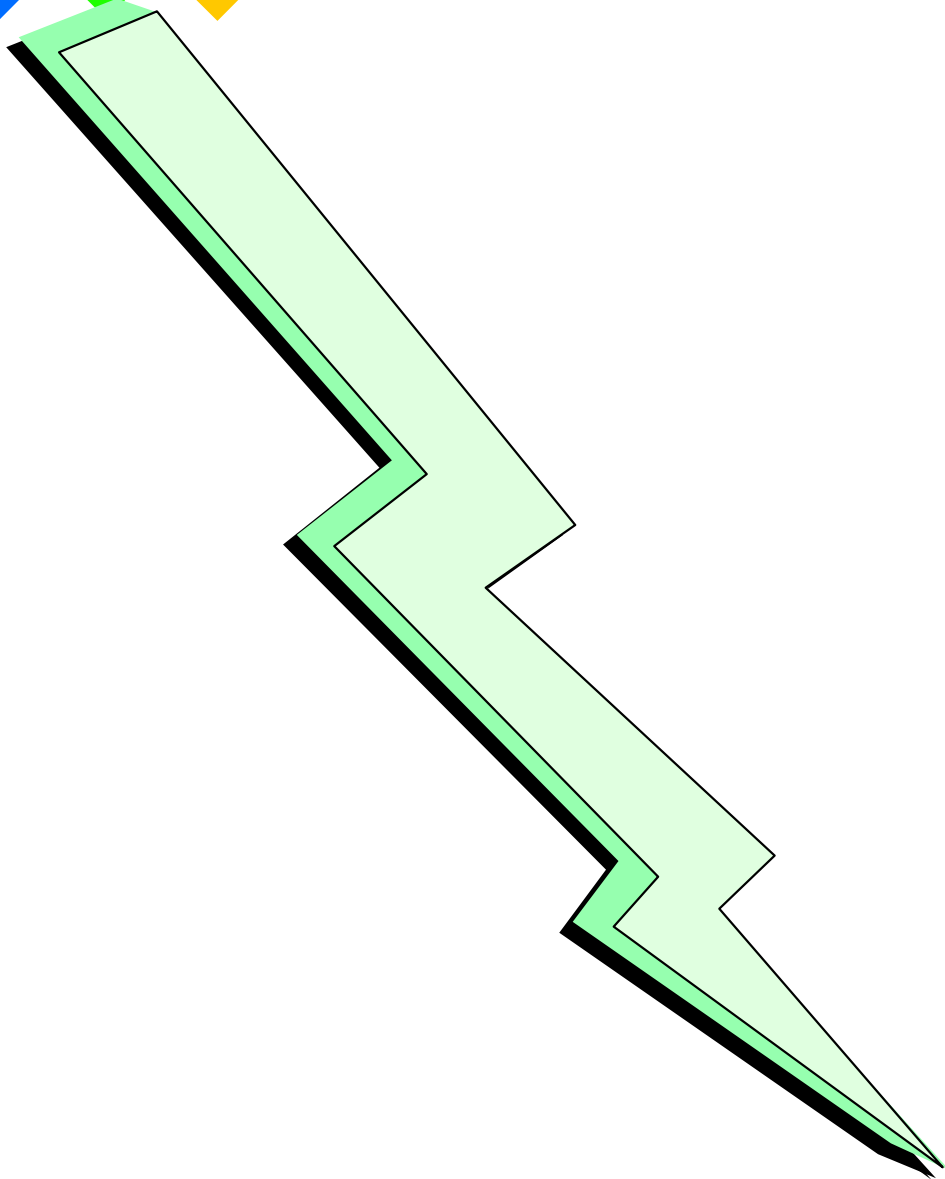
- Example: address space
- Representing and operating on large sets becomes an issue

- **Hierarchy of constraints** [Borning et al., '87]

- Mandatory: test case validity
- Non-mandatory: makes the test 'interesting'



And we want it fast ...

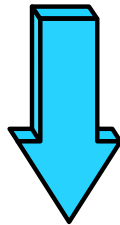




Solution Algorithm: Consistency - A Single Constraint

X **Y** **Z**
{1, 2, 3} **{1, 2, 3}** **{1, 2, 3}**

R: $(x,y,z) \in X \times Y \times Z, x=y+z$



~~**{1, 2, 3}**~~ ~~**{1, 2, 3}**~~ ~~**{1, 2, 3}**~~



Solution Algorithm: Maintaining Arc Consistency (MAC)

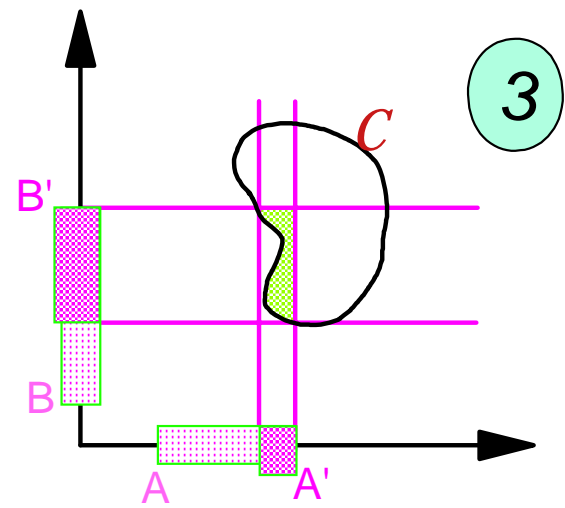
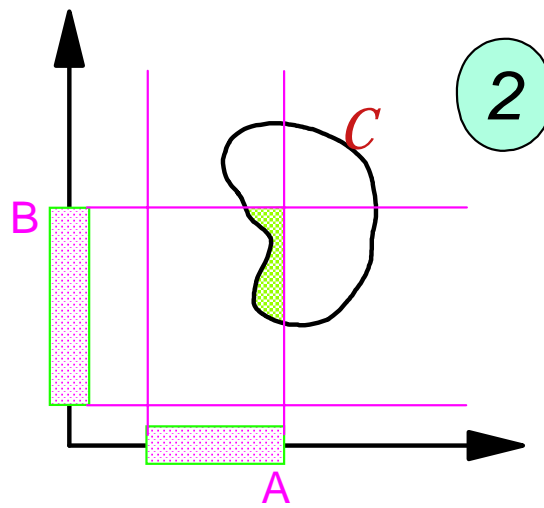
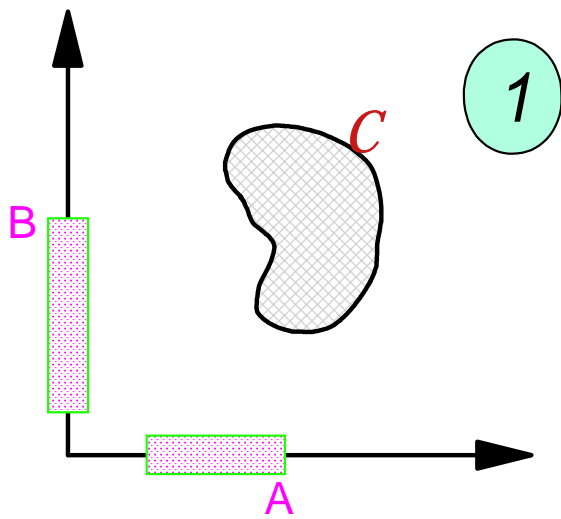
[Mackworth, 1977]

Arc = Constraint

The process: reducing domains to single-values

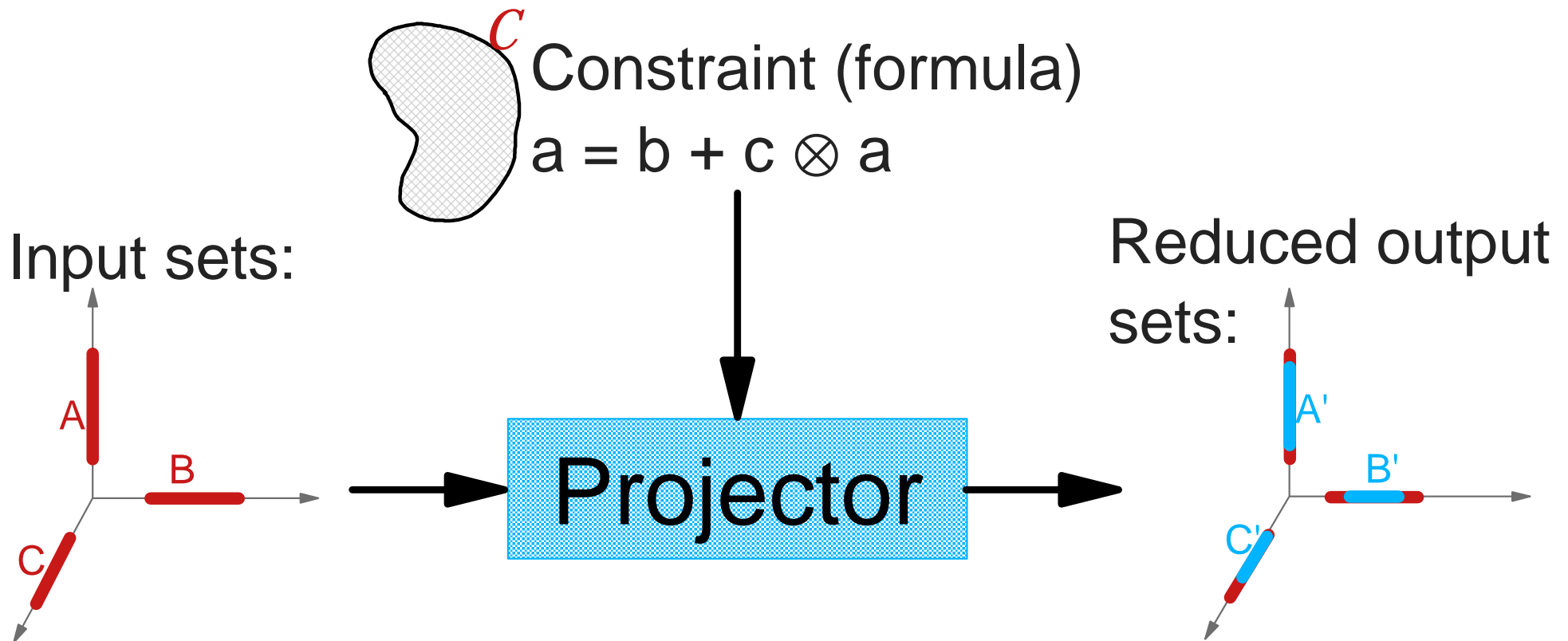
- 1. Make all constraints locally consistent**
 - Some constraints are handled repeatedly
 - Achieve fixed-point
- 2. Choose a variable:** *address*
- 3. Choose a value:** $address \leftarrow 0x1234$
 - $0x1234 \in domain (address)$
- 4. Go to step 1**
- 5. On failure - backtrack**
 - Failure results in an empty set / domain

 Consistency as Projection



Formula Based Constraint Projector

- MAC scheme – projectors for constraints
- Developing arithmetic / logical / bit-wise projectors time after time again ?
 - $a=b+c$, $a+b=c+d$, $a + b = c \textit{ bit-xor} d$, ...
 - Error prone, labour intensive





Example: Projecting Disjoint Constraints

Constraint: $(a=b) \vee (b=a+c) \vee (c=3 \cdot a)$

Domains: $A=\{1,2,3\}; B=\{3,4,5\}; C=\{4,5\}$

(1) Project sub-constraints separately

(2) Join* sub-constraints projections

	A	B	C
Input domain	$\{1,2,3\}$	$\{3,4,5\}$	$\{4,5\}$
$a=b$	$\{3\}$	$\{3\}$	-
$b=a+c$	$\{1\}$	$\{5\}$	$\{4\}$
$c=3a$	ϕ	-	ϕ
Results	$\{1,3\}$	$\{3,5\}$	$\{4,5\}$



Domain (Set) Representation Example: bit-vectors

- **Origin of the challenge: large H/W resources**
 - 128-bit registers
 - 64-bit wide memory address space
- **All the addresses such that**
 - $\text{addr} = \text{base} + \text{displacement}$ // architectural
 - $\text{addr}[3:6] = 01?1$ // cache line
 - $\text{addr} \in [0x2000 : 0x10FFF]$ // memory space
- **'Masks' (DNF) representation:**
 - $01?1 \rightarrow 0101, 0111$



Problem: Exponential Explosion

- **01010101 + 0?0?0?0? →**
 - {10101010, 01101010, 10011010, 01011010, 10100110, 01100110, ..., 10010101}
- **The general case: $a + b \rightarrow 2^{(n/2)}$ clauses**
- **Coping with the problem**
 - Binary Decision Diagrams (BDDs)
 - Sometimes: space explosion
 - Approximations

We only have partial solutions



Summary

- **Viewing test generation as CSP**
- **Characteristics: random, huge domains**
- **Solution scheme**
 - Consistency based
- **HRL's test generators are CSP based**
 - The basis for test generators for all the processors designed in IBM

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End of Presentation

12-Sep-02

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Floating Point Operations – Stochastic Approach

- $a \cdot 2^a \text{ op } b \cdot 2^b = c \cdot 2^c$
 - op: +, -, ·, ...
 - Limited number of bits:
non-continuous domain, rounding

■ Constraints:

- 'op' itself
- bit # n = '0'
- Number of '1's = m
- $a \in [a_1 \dots a_2]$



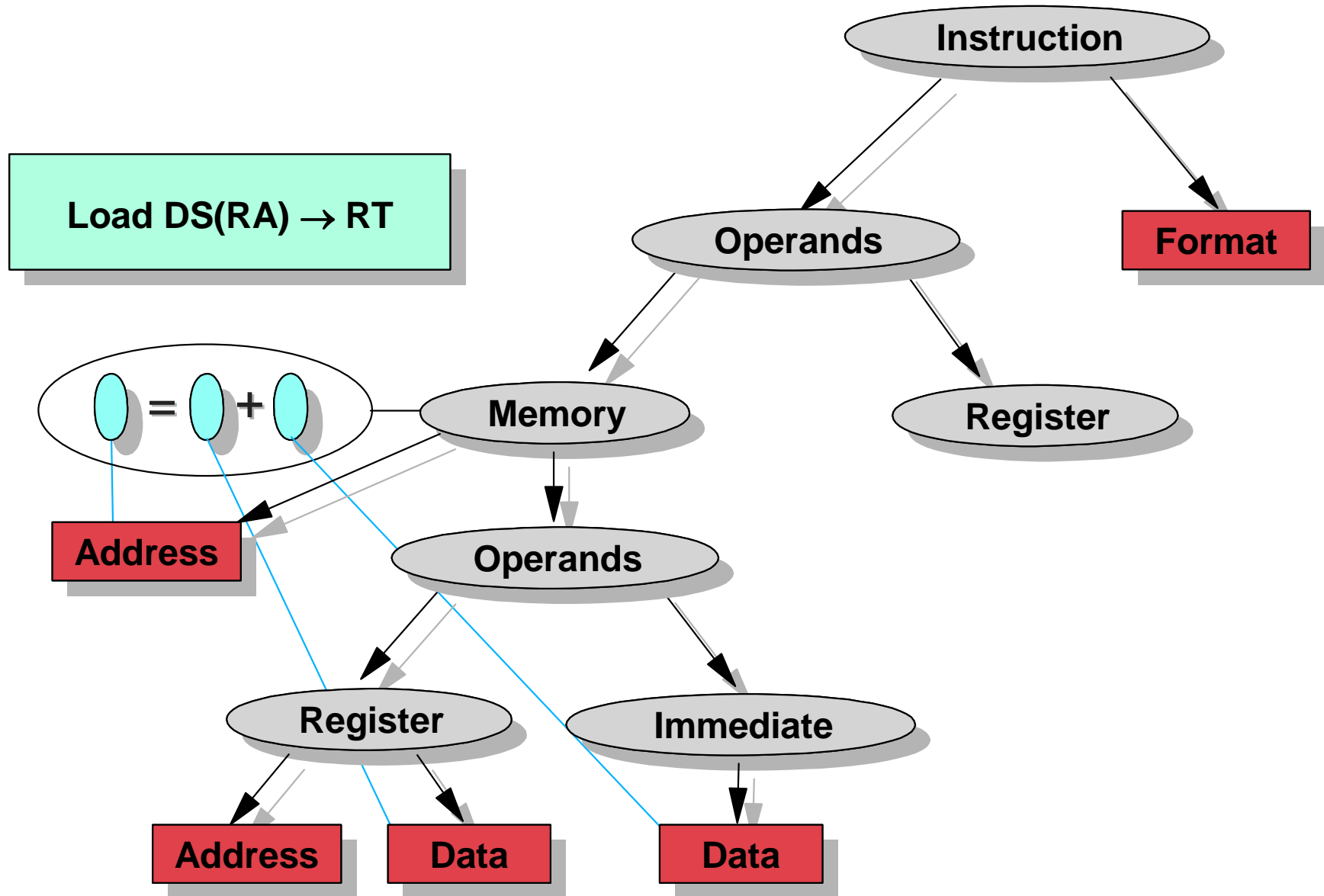
Stochastic solution scheme:

- assign random 64×3 bits
- Hill-climbing
 - Simple heuristics
 - Local maximum: flip random bits
 - After some time - give up and start all over again



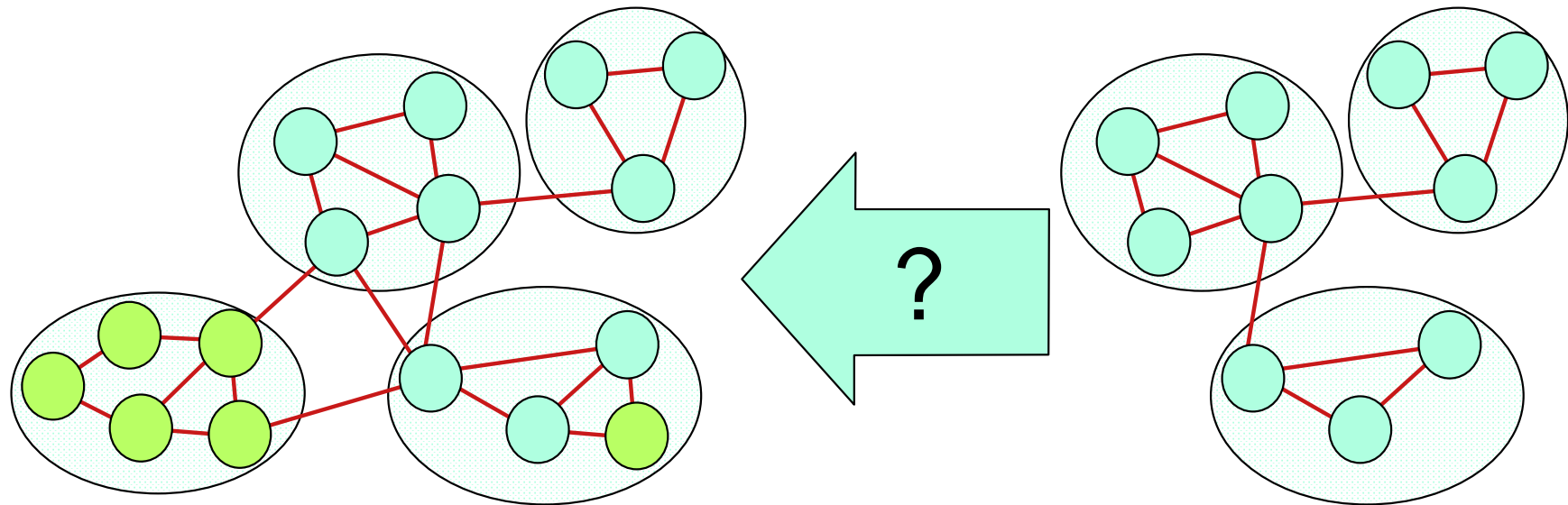
Instruction Constraints

Modelling a PowerPC instruction



Problem Partition, Dynamic Modeling

- **Partitioning the problem**
 - Easier to model, easier to solve
 - Hard to handle interdependencies
- **Dynamic problem structure**





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 - (load n bytes) \Rightarrow (align address to n bytes boundary)
 - $\text{value}(\text{base_reg}) + \text{displacement} = \text{address}$
 - last_instruction = "branch" ?
 - yes: PC = branch-target
 - no : PC = increase (last_instruction_address)